

Low-rank Solution Algorithms for Stochastic Partial Differential Equations

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Overview

- 1 Introduction
 - Problem definition
- 2 Model problem
 - KL expansion
 - Stochastic Galerkin method
 - Tensor format
- 3 Preliminary work
 - Low-rank projection method in tensor format
 - Truncation methods
 - Numerical experiments
- 4 Proposed work
 - Nonlinear random fields
 - Truncation based on randomized tensor decomposition
 - Active subspace methods

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Partial Differential Equations with Stochastic Coefficients

Examples:

Diffusion equations:

$$-\nabla \cdot (a(\mathbf{x}, \xi) \nabla u) = f$$

Convection-diffusion equations:

$$\nu \nabla \cdot (a(\mathbf{x}, \xi) \nabla u) + \vec{w} \cdot \nabla u = f$$

Posed on $D \subset \mathbb{R}^d$ with suitable boundary conditions

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- The impossibility of an exhaustive deterministic description e.g., groundwater flow through a heterogeneous porous media

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- The impossibility of an exhaustive deterministic description e.g., groundwater flow through a heterogeneous porous media
- $a(\mathbf{x}, \xi)$ is a random process/ random field parameterized by a set of random variables $\xi = [\xi_1, \dots, \xi_M]^T$
- The numerical solution $u(\mathbf{x}, \xi)$ can be described by ξ

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Goal:

Efficient computation of the numerical solution $u(\mathbf{x}, \xi)$ and solution statistics (e.g., $\mathbb{E}[u]$, $\text{Var}(u)$) using linear algebraic algorithms

Linear systems:

Large linear systems arise from discretizations of stochastic PDEs:

$$Au = f$$

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Linear systems:

Large linear systems arise from discretizations of stochastic PDEs:

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- High-dimensional problem: a large M in $\xi = [\xi_1, \dots, \xi_M]^T$
- Linear systems with a special structure,

$$A = \sum_{i=1}^M G_i \otimes K_i$$

where \otimes is the Kronecker-product:

$$G \otimes K = \begin{bmatrix} g_{11}K & \cdots & g_{1n_\xi}K \\ \vdots & \ddots & \vdots \\ g_{n_\xi 1}K & \cdots & g_{n_\xi n_\xi}K \end{bmatrix} \in \mathbb{R}^{n_\xi n_x \times n_\xi n_x},$$
$$G \in \mathbb{R}^{n_\xi \times n_\xi} \quad \text{and} \quad K \in \mathbb{R}^{n_x \times n_x}$$

Low-rank solution of linear systems:

Solutions in the Kronecker-product structure:

$$u = \sum_{k=1}^{\kappa_u} y_k \otimes z_k, \quad y_k \in \mathbb{R}^{n_\xi} \text{ and } z_k \in \mathbb{R}^{n_x}$$

where κ_u is the rank of u

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Low-rank approximations to solutions:

$$u \approx \tilde{u} = \sum_{k=1}^{\kappa_{\tilde{u}}} \tilde{y}_k \otimes \tilde{z}_k, \quad \tilde{y}_k \in \mathbb{R}^{n_\xi} \text{ and } \tilde{z}_k \in \mathbb{R}^{n_x}$$

where $\kappa_{\tilde{u}} \ll \kappa_u$ s.t. $\|A\tilde{u} - f\|_2 / \|f\|_2 < \epsilon$

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Karhunen-Loève expansion

Random field $a(\mathbf{x}, \xi)$:
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Karhunen-Loève expansion

Random field $a(\mathbf{x}, \xi)$: $-\nabla \cdot (a(\mathbf{x}, \xi) \nabla u(\mathbf{x}, \xi)) = f$
 $a(\mathbf{x}, \xi)$ has affine dependence on $\{\xi_i\}_{i=1}^M$,

$$a(\mathbf{x}, \xi) \approx a^{(M)}(\mathbf{x}, \xi) = a_0(\mathbf{x}) + \sum_{i=1}^M a_i(\mathbf{x}) \xi_i$$

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In this study, a truncated Karhunen-Loève expansion is considered,

$$a(\mathbf{x}, \xi) \approx a^{(M)}(\mathbf{x}, \xi) = \mu + \sigma \sum_{i=1}^M \sqrt{\lambda_i} a_i(\mathbf{x}) \xi_i$$

- (μ, σ^2) are mean and variance of $a(\mathbf{x}, \xi)$
- $\{(\lambda_i, a_i)\}_{i=1}^M$ are eigenvalue and eigenfunction pairs of an integral operator of covariance function, $C(\mathbf{x}, \mathbf{y})$, $\mathbf{x}, \mathbf{y} \in D$, of $a(\mathbf{x}, \xi)$
- $\{\xi_i\}_{i=1}^M$ are uncorrelated random variables (additional assumption: i.i.d.)

Eigenpairs $\{(\lambda_i, a_i)\}_{i=1}^M$ can be obtained by solving:

$$\int_D C(\mathbf{x}, \mathbf{y}) a_i(\mathbf{y}) d\mathbf{y} = \lambda_i a_i(\mathbf{x}), \quad i = 1 \dots, M$$

The series converges in L^2 sense:

$$\lim_{M \rightarrow \infty} \left\langle \left(a(\mathbf{x}, \xi) - a^{(M)}(\mathbf{x}, \xi) \right)^2 \right\rangle_{\rho} = 0$$

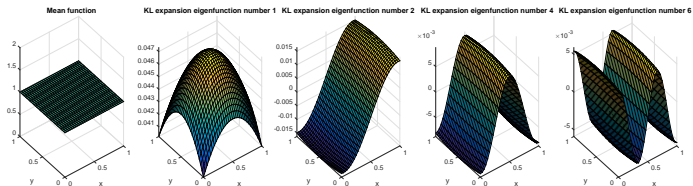


Figure: Mean function and example eigenfunctions

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Solution $u(\mathbf{x}, \xi)$: $-\nabla \cdot (a(\mathbf{x}, \xi) \nabla u(\mathbf{x}, \xi)) = f$
Generalized polynomial chaos expansion:

$$u(\mathbf{x}, \xi) \approx \sum_{s=1}^{n_\xi} u_s(\mathbf{x}) \psi_s(\xi)$$

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- Orthogonality basis: $\int_{\Gamma} \psi_i(\xi) \psi_j(\xi) \rho(\xi) d\xi = \delta_{ij}$

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- Orthogonality basis: $\int_{\Gamma} \psi_i(\xi) \psi_j(\xi) \rho(\xi) d\xi = \delta_{ij}$
- Product form: $\psi_s(\xi) = \psi_{\alpha(s)}(\xi) = \prod_{i=1}^M \pi_{\alpha_i(s)}(\xi_i)$,
 $\alpha(s) = (\alpha_1(s), \dots, \alpha_M(s))$

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- Total degree space:

$$\Lambda^{M,p} = \{\alpha(s) \in \mathbb{N}_0^M : \|\alpha(s)\|_1 \leq p\},$$

where $\|\alpha(s)\|_1 = \sum_{k=1}^M \alpha_k(s)$ and $n_\xi = \dim(\Lambda^{M,p}) = \frac{(M+p)!}{M!p!}$ (DoFs of stochastic domain)

If $\{\xi_i\}$ are uniform random variables
 $\{\pi_i\}$ are Legendre polynomials.

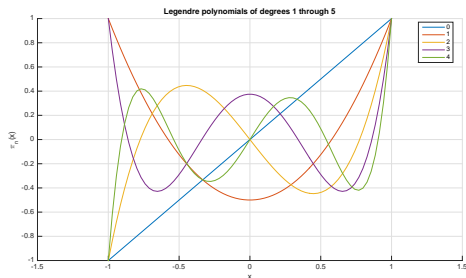
$$\pi_0(\xi_i) = 1,$$

$$\pi_1(\xi_i) = \xi_i,$$

$$\pi_2(\xi_i) = \frac{1}{2}(3\xi_i^2 - 1),$$

$$\pi_3(\xi_i) = \frac{1}{2}(5\xi_i^3 - 3\xi_i)$$

$$\pi_4(\xi_i) = \frac{1}{8}(35\xi_i^4 - 30\xi_i^2 + 3)$$



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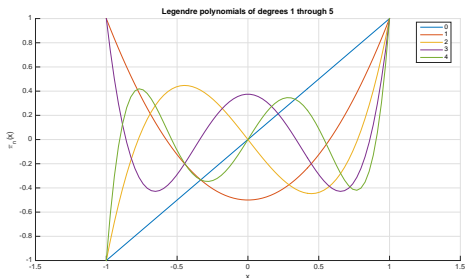
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$$\begin{aligned}\Lambda^{2,3} &= \{(\alpha_1(s), \alpha_2(s))\}_{s=1}^{10} \\ &= \{(0, 0), (1, 0), (2, 0), (3, 0), (0, 1), (1, 1), (2, 1), (0, 2), (1, 2), (0, 3)\}\end{aligned}$$

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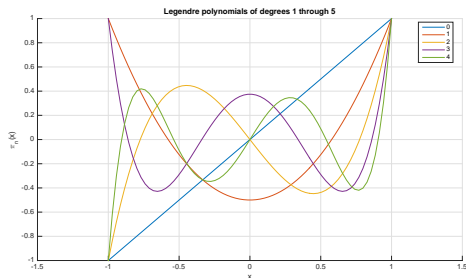
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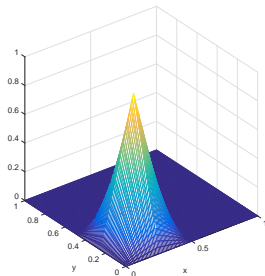
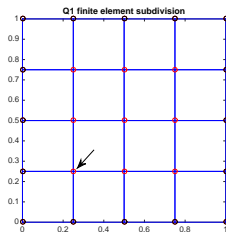
and $n_\xi = 10$

Solution: $u(\mathbf{x}, \xi) \approx \sum_{s=1}^{n_\xi} u_s(\mathbf{x}) \psi_s(\xi)$

Finite Element Methods:

$$u_s(\mathbf{x}) \approx \sum_{r=1}^{n_x} u_{rs} \phi_r(\mathbf{x})$$

using piecewise linear “hat functions”



of nodes = n_x (DoFs of deterministic domain)

The Stochastic Galerkin Method

Discrete solution:

- Discretization in physical space (Finite Element Methods): basis $\{\phi_r\}_{r=1}^{n_x}$, piecewise linear “hat functions”
- Discretization in stochastic space (Polynomial Chaos Expansion): basis $\{\psi_s\}_{s=1}^{n_\xi}$, M -variate polynomials in ξ of total degree p

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$$u^{(sg)}(\mathbf{x}, \xi) = \sum_{s=1}^{n_\xi} \sum_{r=1}^{n_x} u_{rs} \phi_r(\mathbf{x}) \psi_s(\xi)$$

The weak formulation leads to a large coupled system order of $n_x n_\xi$

$$Au = f$$

where $u = [u_{11} \dots u_{n_x 1} \ u_{12} \dots u_{n_x 2} \ \dots \ u_{1n_\xi} \dots u_{n_x n_\xi}]^T$

The Stochastic Galerkin Method

Strong formulation: $-\nabla \cdot (a(\mathbf{x}, \xi) \nabla u(\mathbf{x}, \xi)) = f$

(Deterministic) weak formulation: find $u \in H_E^1(D)$ s.t.

$$\int_D a \nabla u \nabla v \, d\mathbf{x} = \int_D f v \, d\mathbf{x}, \quad \forall v \in H_0^1(D)$$

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Stochastic weak formulation: find $u \in H_E^1(D) \otimes L_2(\Gamma)$ s.t.

$$\int_{\Gamma} \int_D a \nabla u \nabla v \, d\mathbf{x} \rho(\xi) d\xi = \int_{\Gamma} \int_D f v \, d\mathbf{x} \rho(\xi) d\xi, \quad \forall v \in H_0^1(D) \otimes L_2(\Gamma)$$

where $\Gamma = \prod \Gamma_i$ and $\Gamma_i = \xi_i(\Omega)$

LHS:

Substituting the truncated KL expansion $a(\mathbf{x}, \xi) = a_0(\mathbf{x}) + \sum_{i=1}^M a_i(\mathbf{x})\xi_i$:

$$\int_{\Gamma} \int_D \left(a_0(\mathbf{x}) + \sum_{i=1}^M a_i(\mathbf{x})\xi_i \right) \nabla u^{(sg)}(\mathbf{x}, \xi) \nabla v \, d\mathbf{x} \rho(\xi) d\xi$$

Substituting $u^{(sg)}$ and v :

$$\int_{\Gamma} \int_D \left(a_0(\mathbf{x}) + \sum_{i=1}^M a_i(\mathbf{x})\xi_i \right) \nabla \left(\sum_{s=1}^{n_{\xi}} \sum_{r=1}^{n_x} u_{rs} \phi_r(\mathbf{x}) \psi_s(\xi) \right) \nabla \phi_i(\mathbf{x}) \psi_j(\xi) \, d\mathbf{x} \rho(\xi) d\xi,$$
$$i = 1, \dots, n_x, j = 1, \dots, n_{\xi}$$

RHS:

Substituting v :

$$\int_{\Gamma} \int_D f \phi_i(\mathbf{x}) \psi_j(\xi) \, d\mathbf{x} \rho(\xi) d\xi, \quad i = 1, \dots, n_x, j = 1, \dots, n_{\xi}$$

Stochastic Galerkin systems in the Kronecker-product structure:

$$Au = f$$
$$A = G_0 \otimes K_0 + \sum_{l=1}^M G_l \otimes K_l, \quad f = g_0 \otimes f_0$$

“Stochastic” matrices:

$$[G_0]_{ij} = \langle \psi_i(\xi) \psi_j(\xi) \rangle_\rho, \quad [G_l]_{ij} = \langle \xi_l \psi_i(\xi) \psi_j(\xi) \rangle_\rho, \quad l = 1, \dots, M$$

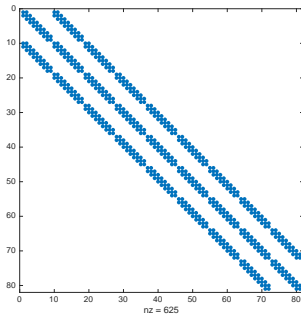
Weighted stiffness matrices:

$$[K_0]_{ij} = \int_D a_0 \nabla \phi_i(\mathbf{x}) \nabla \phi_j(\mathbf{x}) d\mathbf{x},$$
$$[K_l]_{ij} = \int_D a_l(\mathbf{x}) \nabla \phi_i(\mathbf{x}) \nabla \phi_j(\mathbf{x}) d\mathbf{x}, \quad l = 1, \dots, M$$

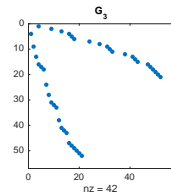
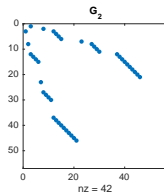
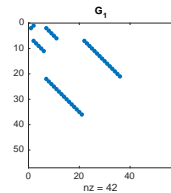
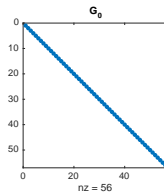
Forcing term:

$$[f_0]_i = \int_D f \phi_i(\mathbf{x}) d\mathbf{x}, \quad [g_0]_i = \langle \psi_i(\xi) \rangle_\rho$$

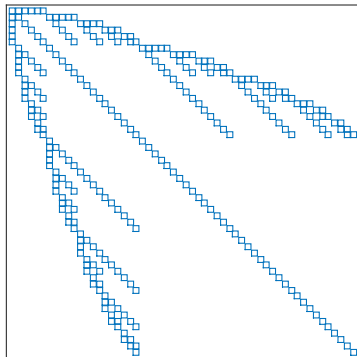
Nonzero structures of matrices:



Stiffness matrices $\{K_i\}_{i=0}^M$



Stochastic matrix $\{G_i\}_{i=1}^3$



Galerkin matrix A (each block has dimension $n_x \times n_x$)

Solutions in tensor format:

$$Au = f,$$

$$u = \sum_{k=1}^{\kappa_u} z_k \otimes y_k, \quad z_k \in \mathbb{R}^{n_\xi} \text{ and } y_k \in \mathbb{R}^{n_x},$$

or, equivalently,

$$U = \sum_{k=1}^{\kappa_u} y_k z_k^T = Y_{\kappa_u} Z_{\kappa_u}^T$$

where

$$Y_{\kappa_u} = [y_1, \dots, y_{\kappa_u}] \in \mathbb{R}^{n_x \times \kappa_u}, \quad Z_{\kappa_u} = [z_1, \dots, z_{\kappa_u}] \in \mathbb{R}^{n_\xi \times \kappa_u}$$

Isomorphism between $\mathbb{R}^{n_x \times n_\xi}$ and $\mathbb{R}^{n_x n_\xi}$ defined by two operators:
 $u = \text{vec}(U)$ and $U = \text{mat}(u)$

$$\begin{bmatrix} u_{11} \\ \vdots \\ u_{n_x 1} \\ u_{12} \\ \vdots \\ u_{n_x 2} \\ \vdots \\ u_{1n_\xi} \\ \vdots \\ u_{n_x n_\xi} \end{bmatrix} \in \mathbb{R}^{n_x n_\xi} \Leftrightarrow \begin{bmatrix} u_{11} & u_{12} & \cdots & u_{1n_\xi} \\ \vdots & \vdots & & \vdots \\ u_{n_x 1} & u_{n_x 2} & \cdots & u_{n_x n_\xi} \end{bmatrix} \in \mathbb{R}^{n_x \times n_\xi}$$

$$= \begin{bmatrix} | & | & \cdots & | \\ y_1 & y_2 & & y_{\kappa_u} \\ | & | & & | \end{bmatrix} \begin{bmatrix} -z_1^T - \\ -z_2^T - \\ \vdots \\ -z_{\kappa_u}^T - \end{bmatrix}$$

Linear systems in tensor format: $Au = f$

$$\left(\sum_{l=0}^M G_l \otimes K_l \right) \left(\sum_{k=1}^{\kappa_u} z_k \otimes y_k \right) = g_0 \otimes f_0$$

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$$\left(\sum_{l=0}^M G_l \otimes K_l \right) \left(\sum_{k=1}^{\kappa_u} z_k \otimes y_k \right) = g_0 \otimes f_0$$
$$\sum_{l=0}^M \sum_{k=1}^{\kappa_u} (G_l z_k) \otimes (K_l y_k) = g_0 \otimes f_0$$

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$$\left(\sum_{l=0}^M G_l \otimes K_l \right) \left(\sum_{k=1}^{\kappa_u} z_k \otimes y_k \right) = g_0 \otimes f_0$$
$$\sum_{l=0}^M \sum_{k=1}^{\kappa_u} (G_l z_k) \otimes (K_l y_k) = g_0 \otimes f_0$$

Matricizing

$$\sum_{l=0}^M \sum_{k=1}^{\kappa_u} (K_l y_k) (G_l z_k)^T = \sum_{l=0}^M \sum_{k=1}^{\kappa_u} K_l y_k z_k^T G_l^T = f_0 g_0^T$$
$$\sum_{l=0}^M K_l U G_l^T = \sum_{l=0}^M (K_l Y_{\kappa_u}) (G_l Z_{\kappa_u})^T = f_0 g_0^T$$

Stochastic Galerkin system:

Exploiting the properties of the Kronecker product structure:

$$Au = \left(\sum_{l=0}^M G_l \otimes K_l \right) \left(\sum_{k=1}^{\kappa_u} z_k \otimes y_k \right) = \sum_{l=0}^M \sum_{k=1}^{\kappa_u} (G_l z_k) \otimes (K_l y_k)$$

- Operation counts of matrix operations are additive
 $O(\text{nnz}(G) + \text{nnz}(K))$ instead of $O(\text{nnz}(G) \times \text{nnz}(K))$
- This motivates the use of Krylov subspace methods in tensor format

Basic operations in tensor notation

Two essential operations for Krylov subspace methods: matrix-vector product and linear combination

- MVP: $\kappa_u \mapsto (M+1)\kappa_u$

$$Au = \sum_{l=0}^M \sum_{k=1}^{\kappa_u} (G_l z_k) \otimes (K_l y_k) = \sum_{i=1}^{(M+1)\kappa_u} \tilde{z}_i \otimes \tilde{y}_i$$

- Addition/subtraction: $(\kappa_u, \kappa_v) \mapsto (\kappa_u + \kappa_v)$

$$u + v = \sum_{i=1}^{\kappa_u} z_i \otimes y_i + \sum_{j=1}^{\kappa_v} \hat{z}_j \otimes \hat{y}_j = \sum_{i=1}^{\kappa_u + \kappa_v} z_i \otimes y_i$$

where $y_{i+\kappa_u} = \hat{y}_i$ and $z_{i+\kappa_u} = \hat{z}_i$, $i = 1, \dots, \kappa_v$

Two of the fundamental operations used in Krylov subspace methods tend to increase the rank of the quantities produced

$$u \Rightarrow \tilde{u}$$
$$\text{Rank} : \kappa_u \Rightarrow \kappa_{\tilde{u}}$$

$$Y : \left[\begin{array}{c|c|c|c} | & | & \cdots & | \\ y_1 & y_2 & & y_{\kappa_u} \\ | & | & & | \end{array} \right] \Rightarrow \left[\begin{array}{c|c|c|c|c|c} | & | & \cdots & | & \cdots & | \\ \tilde{y}_1 & \tilde{y}_2 & & \tilde{y}_{\kappa_u} & & \tilde{y}_{\kappa_{\tilde{u}}} \\ | & | & & | & & | \end{array} \right]$$

$$Z : \left[\begin{array}{c|c|c|c} | & | & \cdots & | \\ z_1 & z_2 & & z_{\kappa_u} \\ | & | & & | \end{array} \right] \Rightarrow \left[\begin{array}{c|c|c|c|c|c} | & | & \cdots & | & \cdots & | \\ \tilde{z}_1 & \tilde{z}_2 & & \tilde{z}_{\kappa_u} & & \tilde{z}_{\kappa_{\tilde{u}}} \\ | & | & & | & & | \end{array} \right]$$

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The GMRES method

The generalized minimum residual method

Compute an approximate solution $u_m \in u_0 + \mathcal{K}_m(A, v_1)$ on m th Krylov subspace, $\mathcal{K}_m = \text{span}\{v_1, Av_1, \dots, A^{m-1}v_1\}$
 u_0 is an initial vector with residual $r_0 = f - Au_0$, $v_1 = r_0 / \|r_0\|_2$

Algorithm 1 GMRES method without restarting

set the initial solution u_0

$$r_0 := f - Au_0$$

$$\tilde{v}_1 := r_0$$

$$v_1 := \tilde{v}_1 / \|\tilde{v}_1\|$$

for $j = 1, \dots, m$ **do**

$$w_j := Av_j$$

$$\text{solve } (V_j^T V_j)\alpha = V_j^T w_j$$

$$\tilde{v}_{j+1} := w_j - \sum_{i=1}^j \alpha_i v_i$$

$$v_{j+1} := \tilde{v}_{j+1} / \|\tilde{v}_{j+1}\|$$

end for

$$\text{solve } (W_m^T AV_m)y = W_m^T r_0 \quad (W_m = AV_m)$$

$$u_1 := u_0 + V_m y$$

Low-rank projection method

Goal: compute a low-rank solution of rank κ satisfying

$$\|f - A\tilde{u}\|_2 / \|f\|_2 < \epsilon$$

Low-rank projection method

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Low-rank projection method

Goal: compute a low-rank solution of rank κ satisfying $\|f - A\tilde{u}\|_2 / \|f\|_2 < \epsilon$ (and maintain rank of all vectors to be κ)

- 1 Construct a new basis vector $w_j = Av_j$
- 2 Orthogonalize w_j with respect to the previously generated basis vectors $\{v_i\}_{i=1}^j$ (i.e., $\hat{w}_j = w_j - \sum_{i=1}^j \alpha_i v_i$ where $V_j^T V_j \alpha = V_j^T w_j$)

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- 3 Truncate the new vector $\tilde{v}_{j+1} = \mathcal{T}_\kappa(\hat{w}_j)$ and orthonormalize $v_{j+1} = \tilde{v}_{j+1} / \|\tilde{v}_{j+1}\|_2$

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- 4 Compute the iterate ($\tilde{u}_1 = \tilde{u}_0 + V_m \beta$) by projecting the residual $r_0 = b - Au_0$ onto the subspace $\mathcal{W}_m = \text{span}\{w_1, \dots, w_m\}$
 $(W_m^T AV_m)\beta = W_m^T r_0$

Low-rank projection method

Goal: compute a low-rank solution of rank κ satisfying

$\|f - A\tilde{u}\|_2 / \|f\|_2 < \epsilon$ (and maintain rank of all vectors to be κ)

- 1 Construct a new basis vector $w_j = Av_j$
 - 2 Orthogonalize w_j with respect to the previously generated basis vectors $\{v_i\}_{i=1}^j$ (i.e., $\hat{w}_j = w_j - \sum_{i=1}^j \alpha_i v_i$ where $V_j^T V_j \alpha = V_j^T w_j$)
 - 3 Truncate the new vector $\tilde{v}_{j+1} = \mathcal{T}_\kappa(\hat{w}_j)$ and orthonormalize $v_{j+1} = \tilde{v}_{j+1} / \|\tilde{v}_{j+1}\|_2$
 - 4 Compute the iterate ($\tilde{u}_1 = \tilde{u}_0 + V_m \beta$) by projecting the residual $r_0 = b - Au_0$ onto the subspace $\mathcal{W}_m = \text{span}\{w_1, \dots, w_m\}$
 $(W_m^T A V_m) \beta = W_m^T r_0$
- Truncation operator \mathcal{T}_κ compresses a tensor of higher rank into one of a desired rank κ
 - Due to truncation, $\mathcal{V}_m = \text{span}\{v_1, \dots, v_m\}$ is not a Krylov subspace
 - If κ is the full rank, the algorithm is the restarted GMRES method

Algorithm 2 Restarted low-rank projection method in tensor format

```
1: set the initial solution  $\tilde{u}_0$ 
2: for  $k = 0, 1, \dots$  do
3:    $r_k := f - A\tilde{u}_k$ 
4:   if  $\|r_k\|/\|f\| < \epsilon$  then
5:     return  $\tilde{u}_k$ 
6:   end if
7:    $\tilde{v}_1 := \mathcal{T}_\kappa(r_k)$ 
8:    $v_1 := \tilde{v}_1/\|\tilde{v}_1\|$ 
9:   for  $j = 1, \dots, m$  do
10:     $w_j := Av_j$ 
11:    solve  $(V_j^T V_j)\alpha = V_j^T w_j$ 
12:     $\tilde{v}_{j+1} := \mathcal{T}_\kappa\left(w_j - \sum_{i=1}^j \alpha_i v_i\right)$ 
13:     $v_{j+1} := \tilde{v}_{j+1}/\|\tilde{v}_{j+1}\|$ 
14:   end for
15:   solve  $(W_m^T AV_m)\beta = W_m^T r_k$ 
16:    $\tilde{u}_{k+1} := \mathcal{T}_\kappa(\tilde{u}_k + V_m\beta)$ 
17: end for
```

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Truncation of a tensor

Truncation operator:

$$\mathcal{T}_\kappa : \kappa' \mapsto \kappa$$

where $\kappa \ll \kappa'$

Truncation of a tensor

Truncation operator:

$$\mathcal{T}_\kappa : \kappa' \mapsto \kappa$$

where $\kappa \ll \kappa'$

$$\begin{bmatrix} | & & | \\ y_1 & \dots & y_{\kappa'} \\ | & & | \end{bmatrix} \begin{bmatrix} -z_1^T- \\ \vdots \\ -z_{\kappa'}^T- \end{bmatrix} \approx \begin{bmatrix} | & & | \\ y_1 & \dots & y_\kappa \\ | & & | \end{bmatrix} \begin{bmatrix} -z_1^T- \\ \vdots \\ -z_\kappa^T- \end{bmatrix}$$

Truncation based on singular values:

Given $U = Y_{\kappa'} Z_{\kappa'}^T$ of rank κ' where $Y_{\kappa'} \in \mathbb{R}^{n_x \times \kappa'}$ and $Z_{\kappa'} \in \mathbb{R}^{n_\xi \times \kappa'}$, compute the singular value decomposition (SVD) of U .

Truncation based on singular values:

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An efficient way to compute the SVD of $U = Y_{\kappa'} Z_{\kappa'}^T$,

- 1 Compute QR factorizations of $Y_{\kappa'}$ and $Z_{\kappa'}$:
 $Y_{\kappa'} = Q_Y R_Y \in \mathbb{R}^{n_x \times \kappa'}$, $Z_{\kappa'} = Q_Z R_Z \in \mathbb{R}^{n_\xi \times \kappa'}$,
- 2 Compute the SVD of $R_Y R_Z^T$:
 $R_Y R_Z^T = \hat{U}_{\kappa'} \hat{\Sigma}_{\kappa'} \hat{V}_{\kappa'}^T = \sum_{k=1}^{\kappa'} \hat{\sigma}_k \hat{u}_k \hat{v}_k^T$,
- 3 Truncate the sum with the κ terms to produce \tilde{Y}_κ and \tilde{Z}_κ ,
 $\tilde{Y}_\kappa = Q_Y \hat{U}_\kappa \hat{\Sigma}_\kappa \in \mathbb{R}^{n_x \times \kappa}$, $\tilde{Z}_\kappa = Q_Z \hat{V}_\kappa \in \mathbb{R}^{n_\xi \times \kappa}$.

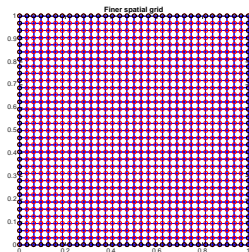
Computationally expensive and an appropriate κ is unknown

Truncation based on multilevel rank-reduction

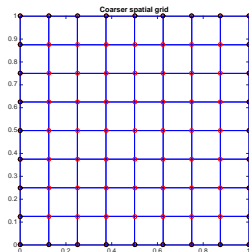
A coarse-spatial grid solution $u^c(\mathbf{x}, \xi)$:

$$u^c(\mathbf{x}, \xi) = (\Phi^c(\mathbf{x}))^T U^c \Psi(\xi) = ((Y^c)^T \Phi^c(\mathbf{x}))^T ((Z^c)^T \Psi(\xi))$$

Recall that $u^{sg}(\mathbf{x}, \xi) = (Y_{\kappa_u}^T \Phi(\mathbf{x}))^T (Z_{\kappa_u}^T \Psi(\xi))$



Finer spatial grid



Coarser spatial grid

Truncation based on multilevel rank-reduction

Multilevel rank-reduction strategy

- Define a truncation operator based on the information obtained from a coarse spatial grid computation: Given $U = Y_{\kappa'} Z_{\kappa'}^T$ of rank κ' ,

$$\mathcal{T}_{\kappa}(U) \equiv (Y_{\kappa'} Z_{\kappa'}^T Z_{\kappa}^c) (Z_{\kappa}^c)^T = \tilde{U}$$

where $\tilde{U} = \tilde{Y}_{\kappa} \tilde{Z}_{\kappa}^T$, $\tilde{Y}_{\kappa} = Y_{\kappa'} Z_{\kappa'}^T Z_{\kappa}^c \in \mathbb{R}^{n_x \times \kappa}$ and $\tilde{Z}_{\kappa} = Z_{\kappa}^c \in \mathbb{R}^{n_{\xi} \times \kappa}$

Truncation based on multilevel rank-reduction

Multilevel rank-reduction strategy

- Define a truncation operator based on the information obtained from a coarse spatial grid computation: Given $U = Y_{\kappa'} Z_{\kappa'}^T$ of rank κ' ,

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where $\tilde{U} = \tilde{Y}_{\kappa} \tilde{Z}_{\kappa}^T$, $\tilde{Y}_{\kappa} = Y_{\kappa'} Z_{\kappa'}^T Z_{\kappa}^c \in \mathbb{R}^{n_x \times \kappa}$ and $\tilde{Z}_{\kappa} = Z_{\kappa}^c \in \mathbb{R}^{n_{\xi} \times \kappa}$

- Identify a desired rank κ s.t.

$$\|f^c - A^c u^{c, \kappa}\|_2 / \|f^c\|_2 \leq \epsilon$$

where $u^{c, \kappa}$ is a κ -term approximation to u^c

- The κ -term approximation on a coarse spatial grid can be computed efficiently using the Proper Generalized Decomposition method

Preconditioning

Preconditioned system:

$$AM^{-1}\hat{u} = f, \quad \hat{u} = M\tilde{u}$$

- Mean-based preconditioner: $M = G_0 \otimes K_0$
- Preconditioned system in tensor notation:

$$AM^{-1}\hat{u} = \sum_{l=0}^M \sum_{k=1}^{\kappa_{\hat{u}}} G_l \hat{z}_k \otimes K_l K_0^{-1} \hat{y}_k$$

- Practical application of the preconditioner: the action of K_0^{-1} is replaced by an application of a single V-cycle of an algebraic multigrid method

With right preconditioning and the AMG preconditioner, the strategy for handling tensor rank is largely unaffected by preconditioning

Algorithm 3 Preconditioned low-rank projection method with the multi-level rank-reduction

- 1: Compute $u^{c, \kappa}$ which satisfies $\frac{\|f^c - A^c u^{c, \kappa}\|_2}{\|f^c\|_2} < \epsilon$ using the PGD method
 - 2: Compute Z_{κ}^c such that $U^{c, \kappa} = Y_{\kappa}^c (Z_{\kappa}^c)^T$ and define $\mathcal{T}_{\kappa}(U) \equiv (UZ_{\kappa}^c)(Z_{\kappa}^c)^T$
 - 3: Run Algorithm 2 with $\mathcal{L} = AM^{-1}$, f , and \mathcal{T}_{κ}
-

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Stochastic diffusion problems

Steady-state diffusion problems with homogeneous Dirichlet boundary condition:

$$\begin{cases} -\nabla \cdot (a(\mathbf{x}, \xi) \nabla u(\mathbf{x}, \xi)) = f(\mathbf{x}, \xi) & \text{in } D \times \xi, \\ u(\mathbf{x}, \xi) = 0 & \text{on } \partial D \times \Gamma, \end{cases}$$

with $f(\mathbf{x}, \xi) = 1$.

Covariance function of $a(\mathbf{x}, \xi)$:

$$C(\mathbf{x}, \mathbf{y}) = \sigma^2 \exp \left(-\frac{|\mathbf{x}_1 - \mathbf{y}_1|}{c} - \frac{|\mathbf{x}_2 - \mathbf{y}_2|}{c} \right)$$

The truncated KL-expansion:

$$a(\mathbf{x}, \xi) = \mu + \sigma \sum_{i=1}^M \sqrt{\lambda_i} a_i(\mathbf{x}) \xi_i$$

$\mu = 1$, $\sigma = 0.05$, and M is chosen to capture 95% of the total variance of the random field (i.e., $\sum_{i=1}^M \lambda_i / \sum_{i=1}^{n_x} \lambda_i > 95\%$)

Coarse spatial grid computation:

Table: Rank (κ) of coarse-grid solutions satisfying a specified tolerance ϵ for the PGD computation, and for varying c and M

	$\epsilon = 10^{-5}$				$\epsilon = 10^{-6}$			
c	4	3	2.5	2	4	3	2.5	2
M, n_ξ	5, 56	7, 120	10, 286	15, 816	5, 56	7, 120	10, 286	15, 816
n_x^c	15^2	15^2	31^2	31^2	15^2	15^2	31^2	31^2
Rank(κ)	25	40	65	115	35	65	100	210

n_ξ : DoFs of stochastic domain

n_x^c : DoFs of coarse spatial domain

Fine spatial grid computation:

Table: CPU time to compute approximate solutions satisfying $\epsilon = 10^{-5}$, 10^{-6} using the preconditioned low-rank projection method with the multilevel rank-reduction. Here, t_f is the time to compute the fine-grid solution, t_f , and, t is the total time, $t = t_f + t_c$

n_x	M	$\epsilon = 10^{-5}$				$\epsilon = 10^{-6}$			
		5	7	10	15	5	7	10	15
129^2	t_f	5.87	8.96	20.53	87.07	7.21	14.28	36.85	235.34
	t	8.35	12.43	28.88	132.15	10.14	19.32	51.69	398.06
257^2	t_f	22.69	34.90	84.85	340.51	27.61	56.36	148.07	1014.97
	t	25.17	38.37	93.20	385.59	30.55	61.41	162.90	1177.68
513^2	t_f	144.69	194.41	445.36	2809.54	163.31	310.14	1318.79	OoM
	t	147.17	197.87	453.71	2854.62	166.24	315.18	1333.63	OoM

n_x : DoFs of fine spatial domain

Comparison to a truncation operator based on singular values:

Table: CPU time to compute approximate solutions satisfying $\epsilon = 10^{-5}, 10^{-6}$ using the preconditioned low-rank projection (LRP) methods with the multilevel rank-reduction and the singular value based truncation on the level 8 spatial grid ($n_x = 257^2$)

	Solver	M	5	7	10	15	20
$\epsilon = 10^{-5}$	LRP-SVD	t	55.04	108.11	284.27	1280.65	5691.19
	LRP-Multilevel	t	25.17	38.37	93.20	385.59	1943.49
$\epsilon = 10^{-6}$	LRP-SVD	t	76.03	198.20	564.12	5131.32	OoM
	LRP-Multilevel	t	30.55	61.41	162.90	1177.68	OoM

PGD as a solver on a finer spatial grid:

Table: Computation time to obtain approximate solutions satisfying $\epsilon = 10^{-5}$ using the PGD method and the preconditioned low-rank projection method on the level 8 spatial grid ($n_x = 257^2$)

	Solver	M	5	7	10	15	20
$\epsilon = 10^{-5}$	PGD	κ	25	45	65	125	195
		t	43.78	109.72	228.73	940.69	3066.87
	LRP-Multilevel	κ	25	40	65	115	180
		t	25.17	38.37	93.20	385.59	1943.49
$\epsilon = 10^{-6}$	PGD	κ	40	70	110	225	OoM
		t	74.43	214.82	533.10	2713.70	OoM
	LRP-Multilevel	κ	35	65	100	210	OoM
		t	30.55	61.41	162.90	1177.68	OoM

Stochastic convection-diffusion problems

Steady-state convection-diffusion problems with non-homogeneous boundary condition:

$$\begin{cases} \nu \nabla \cdot (a(\mathbf{x}, \xi) \nabla u(\mathbf{x}, \xi)) + \vec{w} \cdot \nabla u(\mathbf{x}, \xi) = f(\mathbf{x}, \xi) & \text{in } D \times \Gamma, \\ u(\mathbf{x}, \xi) = g_D(\mathbf{x}) & \text{on } \partial D \times \Gamma, \end{cases}$$

where $g_D(\mathbf{x})$ is determined by

$$g_D(\mathbf{x}) = \begin{cases} g_D(x, -1) = x, & g_D(x, 1) = 0, \\ g_D(-1, y) \approx -1, & g_D(1, y) \approx 1, \end{cases}$$

where the latter two approximations hold except near $y = 1$, and ν is the viscosity parameter.

The solution has *exponential boundary layer* near $y = 1$

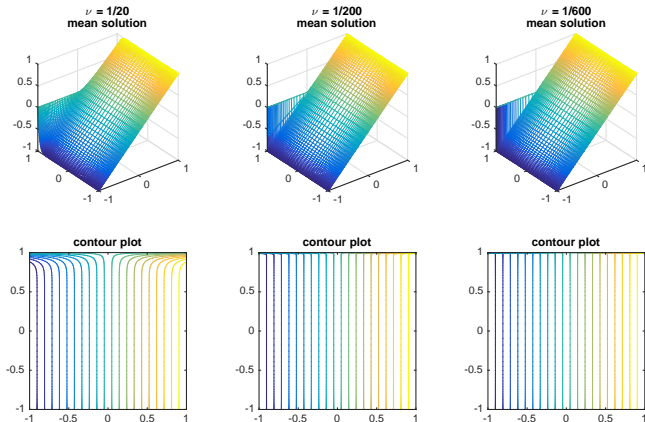


Figure: Mean solutions (top) and their contour plots (bottom) for varying ν

Stochastic Galerkin system:

$$\left(G_0 \otimes \nu K_0 + \sum_{l=1}^M G_l \otimes \nu K_l + G_0 \otimes N + G_0 \otimes S \right) u = g_0 \otimes f_0$$

- the convection term N : $[N]_{ij} = \int_D \vec{w} \cdot \nabla \phi_i(\mathbf{x}) \phi_j(\mathbf{x}) d\mathbf{x}$
- the streamline-diffusion term S : $[S]_{ij} = \sum_{l=1}^{n_e} \delta_l \int_D (\vec{w} \cdot \nabla \phi_i) (\vec{w} \cdot \nabla \phi_j) d\mathbf{x}$
where n_e : the number of element in the finite element discretization
and $\delta_k = \frac{h_k}{2\|\vec{w}\|_2} \left(1 - \frac{1}{\mathcal{P}_k} \right)$ if $\mathcal{P}_k > 1$

Preconditioned system:

Mean-based preconditioner: $M = G_0 \otimes (K_0 + N + S)$

the action of $(K_0 + N + S)$ is replaced by an application of a single V-cycle of an algebraic multigrid method

Comparison to a truncation operator based on singular values:

Table: CPU time to compute approximate solutions satisfying $\epsilon = 10^{-5}, 10^{-6}$ using the preconditioned low-rank projection (LRP) methods with the multilevel rank-reduction and the singular value based truncation on the level 8 spatial grid ($n_x = 257^2$)

ϵ	Solver	M	$\nu = 1/600$				$\nu = 1/20$			
			5	7	10	15	5	7	10	15
10^{-5}	LRP-SVD	t	90.33	103.44	218.35	484.08	68.45	100.83	201.34	448.25
	LRP-Multilevel	t	65.48	73.28	142.46	321.99	51.50	67.24	128.45	291.46
10^{-6}	LRP-SVD	t	122.44	231.07	421.76	1208.88	132.08	234.15	570.56	2055.44
	LRP-Multilevel	t	81.93	107.84	186.56	530.89	83.43	136.69	341.32	1266.53

Table: Computation time and the number of cycles (k) to compute approximate solutions with $\epsilon = 10^{-5}$ and 10^{-6} using the preconditioned low-rank projection methods with the multilevel rank-reduction method for varying ν

		$\epsilon = 10^{-5}$			$\epsilon = 10^{-6}$		
ν	n_x^c	$M = 5$	$M = 7$	$M = 10$	$M = 5$	$M = 7$	$M = 10$
$\frac{1}{20}$	17^2	25	35	55	35	50	75
$\frac{1}{100}$	17^2	20	25	45	30	40	65
$\frac{1}{200}$	33^2	20	25	45	25	40	60
$\frac{1}{400}$	33^2	20	20	35	25	35	55
$\frac{1}{600}$	65^2	20	20	35	30	35	45

n_x^c : DoFs of coarse spatial grid

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Nonlinear random fields

Log-normal random field:

$$a(\mathbf{x}, \xi) = e^{g(\mathbf{x}, \xi)}, \quad g(\mathbf{x}, \xi) = g_0(\mathbf{x}, \xi) + \sum_{i=1}^M g_i(\mathbf{x}) \xi_i$$

where $g(\mathbf{x}, \xi)$ is a truncated KL expansion and $\{\xi_i\}_{i=1}^M$ are independent normal random variables

Polynomial approximation of a random field:

$$a(\mathbf{x}, \xi) = \sum_{\alpha \in \Lambda} a_{\alpha}(\mathbf{x}) \psi_{\alpha}(\xi)$$

where Λ is a multi-index set

Stochastic Galerkin system

Stochastic Galerkin solution: $u^{(sg)}(\mathbf{x}, \xi) = \sum_{s=1}^{n_\xi} \sum_{r=1}^{n_x} u_{rs} \phi_r(\mathbf{x}) \psi_s(\xi)$

Stochastic weak formulation:

$$\int_{\Gamma} \int_D \left(\sum_{\alpha \in \Lambda} a_\alpha(\mathbf{x}) \psi_\alpha(\xi) \right) \nabla \left(\sum_{s=1}^{n_\xi} \sum_{r=1}^{n_x} u_{rs} \phi_r(\mathbf{x}) \psi_s(\xi) \right) \nabla \phi_i(\mathbf{x}) \psi_j(\xi) d\mathbf{x} \rho(\xi) d\xi,$$
$$i = 1, \dots, n_x, j = 1, \dots, n_\xi$$

Stiffness matrices and “stochastic matrices”:

$$[K_I]_{ij} = \int_D a_I \phi_i \phi_j d\mathbf{x}, \quad [G_I]_{ij} = \langle \psi_I \psi_i \psi_j \rangle_\rho.$$

Total degree space for approximating $u^{(sg)}(\mathbf{x}, \xi)$:

$$\Lambda^{M,p} = \{\alpha(s) \in \mathbb{N}_0^M : \|\alpha(s)\|_0 \leq M, \|\alpha(s)\|_1 \leq p\}$$

Polynomial expansion is implicitly truncated with polynomials of total degree $\leq 2p$:

$$a(\mathbf{x}, \xi) \approx \sum_{\alpha \in \Lambda^{M,2p}} a_\alpha(\mathbf{x}) \psi_\alpha(\xi)$$

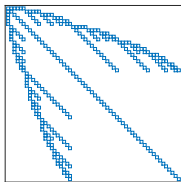
because

$$\langle \psi_i \psi_j \rangle_\rho = 0 \quad \forall i, j \text{ s.t. } \alpha(i), \alpha(j) \in \Lambda^{M,p} \quad \text{if} \quad \sum_k \alpha_k(l) > 2p,$$

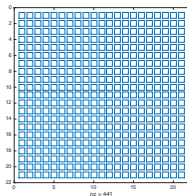
- $n_a = \dim(\Lambda^{M,2p}) = \frac{(M+2p)!}{M!(2p)!}$
- Special case: $n_a = M + 1$

$$a(\mathbf{x}, \xi) \approx \sum_{k=0}^M a_k(\mathbf{x}) \xi_k$$

Block sparse linear system, A :

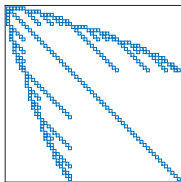


linear RF

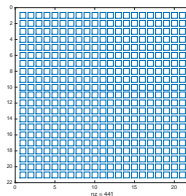


nonlinear RF

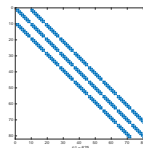
Block sparse linear system, A :



linear RF



nonlinear RF



Each block
is sparse

Two potential directions of the study:

- Use a randomized tensor Interpolative Decomposition as a truncation operator
 - to replace costly SVD
 - when efficient coarse grid computation is impossible
 - ID provides means to approximate a matrix/ tensor in efficient way
- Reduce dimensions of problem using active subspace methods
 - the number of terms in the polynomial expansion of $a(\mathbf{x}, \xi)$ is large
 - Active subspace methods represents a dimension-reduction method that can be used to reduce the number of terms in the expansion

Matrix Interpolative Decomposition

Matrix approximation by a column subset:

$$A \approx A_{CS}[I|T]P^T$$

G matrices are rank-deficient

$$w = Av \text{ where } \text{mat}(v) = Y_v Z_v^T, \text{mat}(w) = Y_w Z_w^T$$

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$$Y_v \in \mathbb{R}^{n_x \times \kappa}, Z_v \in \mathbb{R}^{n_\xi \times \kappa}, Y_w \in \mathbb{R}^{n_x \times \kappa'}, \text{ and } Z_w \in \mathbb{R}^{n_\xi \times \kappa'}$$

- $W = \text{mat}(w)$ is rank deficient
- $Z_w = [G_0 Z_v | G_1 Z_v | \cdots | G_{n_a} Z_v]$, each block is rank deficient
In tensor format, $y \otimes x + z \otimes x = (y + z) \otimes x$

Interpolative decomposition:

$$W \approx W_{CS}[I|T]P^T$$

$$(G_i Z_v) \approx G_{CS}[I|T]P^T$$

Randomization makes the computation efficient without losing too much accuracy

Active subspace methods

Applying active subspace methods on a nonlinear random field:

$$a(\mathbf{x}, \xi) = \exp \left(g_0(\mathbf{x}, \xi) + \sum_{k=1}^M g_k(\mathbf{x}) \xi_k \right) \approx \sum_{\alpha \in \Lambda^{M, 2p}} a_\alpha(\mathbf{x}) \psi_\alpha(\xi)$$

The gradient of $a(\mathbf{x}, \xi)$:

$$\nabla_\xi a(\mathbf{x}, \xi) = \left[\frac{\partial a}{\partial \xi_1}, \dots, \frac{\partial a}{\partial \xi_M} \right]^T$$

where

$$\frac{\partial a}{\partial \xi_i} = \exp \left(g_0(\mathbf{x}, \xi) + \sum_{k=1}^M g_k(\mathbf{x}) \xi_k \right) g_i(\mathbf{x}).$$

The covariance matrix $C(\mathbf{x})$:

$$[C(\mathbf{x})]_{ij} = \mathbb{E} \left[\frac{\partial a}{\partial \xi_i} \frac{\partial a}{\partial \xi_j} \right] = \exp \left(2g_0(\mathbf{x}, \xi) + \sum_{k=1}^M 2g_k^2(\mathbf{x}) \right) g_i(\mathbf{x}) g_j(\mathbf{x}).$$

An eigendecomposition of $C_i = C(x_i) \in \mathbb{R}^{M \times M}$:

$$C_i = W_i \Lambda_i W_i^T$$

A new set of random variable $\{\eta_j^{(i)}\}_{j=1}^M$:

$$\eta^{(i)} = W_i^T \xi \Leftrightarrow W_i \eta^{(i)} = W_i W_i^T \xi = \xi,$$

and $\{\eta^{(i)}\}$ are also independent normal random variables:

$$\mathbb{E} [\eta_j^{(i)}] = \mathbb{E} [\mathbf{w}_j^T \xi] = 0,$$

$$\mathbb{E} [(\eta_j^{(i)})^2] = \mathbb{E} [(\mathbf{w}_j^T \xi)^2] = \|\mathbf{w}_j\|_2^2 = 1,$$

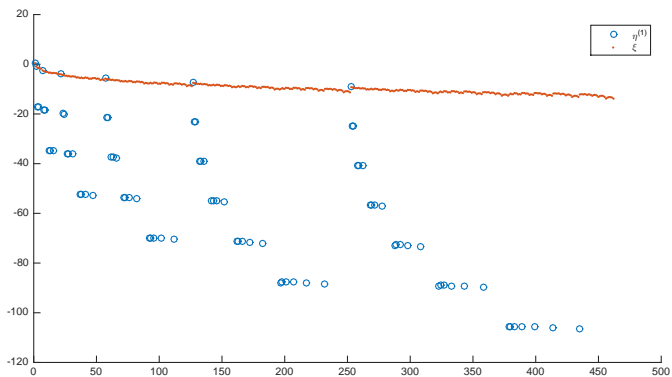
$$\mathbb{E} \left[(\eta_j^{(i)}) (\eta_j^{(i)})^T \right] = \mathbb{E} [W_i^T \xi \xi^T W_i] = W_i^T \mathbb{E} [\xi \xi^T] W_i = I.$$

Change of variable:

$$\begin{aligned} a(x_i, \xi) &= \exp \left(g_0(x_i) + \sum_{k=1}^M g_k(x_i) \xi_k \right) \\ &= \exp \left(g_0(x_i) + \sum_{k=1}^M g_k(x_i) \left(\sum_{l=1}^M w_{kl} \eta_l^{(i)} \right) \right) \\ &= \exp \left(g_0(x_i) + \sum_{k=1}^M \tilde{g}_k(x_i) \eta_k^{(i)} \right), \quad \left(\tilde{g}_k(x_i) = \sum_{l=1}^M g_l(x_i) w_{ik} \right), \\ &= a(x_i, \eta^{(i)}) \end{aligned}$$

A new linear expansion for $a(\mathbf{x}, \xi)$:

$$a(x_i, \xi) = \hat{a}(x_i, \eta^{(i)}) = \sum_{\alpha \in \Lambda^{M, 2p}} \hat{a}_\alpha(x_i) \psi_\alpha(\eta^{(i)})$$



At spatial point x_1 , $\log_{10}(|a_\alpha(x_1)|)$ v.s. $\log_{10}(|\hat{a}_\alpha(x_1)|)$

Thank you!

Coarse Spatial Grid Computation

The Proper Generalized Decomposition method:

- Computes the separated representation of a coarse-grid solution:

$$u^{c, \kappa}(\mathbf{x}, \xi) = \sum_{i=1}^{\kappa} \tilde{y}_i(\mathbf{x}) \tilde{z}_i(\xi)$$

- Discretization in physical space: $\tilde{y}_i(\mathbf{x}) = \sum_{k=1}^{n_x} \tilde{y}_k^{(i)} \phi_k^\xi(\mathbf{x})$
- Discretization in stochastic space: $\tilde{z}_i(\xi) = \sum_{l=1}^{n_\xi} \tilde{z}_l^{(i)} \psi_l(\xi)$

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- Identifies the function pairs $(\tilde{y}_i(\mathbf{x}), \tilde{z}_i(\xi))$ incrementally until the relative residual of the computed solution satisfies a given tolerance, $\|f^c - A^c u^{c, \kappa}\|_2 / \|f^c\|_2 < \epsilon$

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$$\|f^c - A^c u^{c, \kappa}\|_2 / \|f^c\|_2 < \epsilon$$
- Once i such pairs have been computed, $(\tilde{y}_{i+1}, \tilde{z}_{i+1})$ is sought in $X_h \times S_M$ by imposing Galerkin orthogonality with respect to the tangent manifold of the set of rank-one elements at $\tilde{y}_{i+1} \tilde{z}_{i+1}$, which is $\{\tilde{y}_{i+1} \zeta + v \tilde{z}_{i+1}; v \in X_h, \zeta \in S_M\}$: find $\tilde{y}_{i+1} \tilde{z}_{i+1}$ s.t.

$$\left\langle \int_D a(\mathbf{x}, \xi) \nabla(u^{c, i} + \tilde{y}_{i+1} \tilde{z}_{i+1}) \cdot \nabla(\tilde{y}_{i+1} \zeta + v \tilde{z}_{i+1}) \right\rangle = \left\langle \int_D f(\tilde{y}_{i+1} \zeta + v \tilde{z}_{i+1}) \right\rangle,$$

$$\forall (v, \zeta) \in X_h \times S_M$$

- Two coupled problems: a deterministic problem and a stochastic problem

- **Deterministic problem:** given $\tilde{\mathbf{z}}_{i+1}$, find $\tilde{\mathbf{y}}_{i+1} \in X_h$ s.t.

$$\left\langle \int_D \mathbf{a}(\mathbf{x}, \xi) \nabla(u^{c,i} + \tilde{\mathbf{y}}_{i+1} \tilde{\mathbf{z}}_{i+1}) \cdot \nabla(\phi_j^c \tilde{\mathbf{z}}_{i+1}) \right\rangle = \left\langle \int_D f \phi_j^c \tilde{\mathbf{z}}_{i+1} \right\rangle, j = 1, \dots, n_x^c$$

- **Stochastic problem:** given $\tilde{\mathbf{y}}_{i+1}$, finds $\tilde{\mathbf{z}}_{i+1} \in S_M$ s.t.

$$\left\langle \int_D \mathbf{a}(\mathbf{x}, \xi) \nabla(u^{c,i} + \tilde{\mathbf{y}}_{i+1} \tilde{\mathbf{z}}_{i+1}) \cdot \nabla(\tilde{\mathbf{y}}_{i+1} \psi_j) \right\rangle = \left\langle \int_D f \tilde{\mathbf{y}}_{i+1} \psi_j \right\rangle, j = 1, \dots, n_\xi$$

- Enhances accuracy of the κ -term approximation by solving a set of κ coupled equations

- **Update problem:** given $\{\tilde{\mathbf{y}}_i\}_{i=1}^\kappa$, find $\{\tilde{\mathbf{z}}_i\}_{i=1}^\kappa$ s.t.

$$\left\langle \int_D \mathbf{a}(\mathbf{x}, \xi) \nabla(u^{(\kappa)}) \cdot \nabla(\tilde{\mathbf{y}}_i \psi_j) \right\rangle = \left\langle \int_D f \tilde{\mathbf{y}}_i \psi_j \right\rangle, i = 1, \dots, \kappa, j = 1, \dots, n_\xi.$$

Matrix Interpolative Decomposition

QR factorization:

$$\begin{aligned} AP &= QR = \left[\begin{array}{c|c} Q_{11} & Q_{12} \\ \hline Q_{21} & Q_{22} \end{array} \right] \left[\begin{array}{c|c} R_{11} & R_{12} \\ \hline 0 & R_{22} \end{array} \right] \\ &= \left[\begin{array}{c} Q_{11} \\ \hline Q_{21} \end{array} \right] [R_{11}|R_{12}] + \left[\begin{array}{c} Q_{12} \\ \hline Q_{22} \end{array} \right] [0|R_{22}] \\ &= \left[\begin{array}{c|c} Q_{11}R_{11} & \\ \hline Q_{21}R_{11} & \end{array} \right] [I|R_{11}^{-1}R_{12}] + \left[\begin{array}{c|c} 0 & Q_{12}R_{22} \\ \hline 0 & Q_{22}R_{22} \end{array} \right] \\ &= A_{CS}[I|T] + XP \end{aligned}$$

where

$$A_{CS} = \left[\begin{array}{c} Q_{11}R_{11} \\ \hline Q_{21}R_{11} \end{array} \right], \quad T = R_{11}^{-1}R_{12}, \quad X = \left[\begin{array}{c|c} 0 & Q_{12}R_{22} \\ \hline 0 & Q_{22}R_{22} \end{array} \right] P^T$$

$$A \approx \hat{A} = A_{CS}[I|T]P^T,$$
$$\|A - \hat{A}\|_2 = \|X\|_2 \leq \sigma_{k+1}(A)\sqrt{1 + k(n - k)}.$$

$$R = \left[\begin{array}{c|c} R_{11} & R_{12} \\ \hline 0 & R_{22} \end{array} \right]$$

$$\sigma_1(R_{22}) \leq \sigma_{k+1}(A)\sqrt{1 + k(n - k)}.$$

Randomized Matrix Interpolative Decomposition

Randomized scheme for approximating the range $A \in \mathbb{R}^{m \times n}$:

- Draw an $n \times l$ Gaussian random matrix Ω
- Form the matrix product $Y = A\Omega$
- Construct a matrix Q whose columns form an orthonormal basis for the range of Y

Intuition:

$$y^{(i)} = A\omega^{(i)}, \quad i = 1, 2, \dots, k$$

Consider $A = B + E$, where B is a rank- k matrix and E is a small perturbation, then

$$y^{(i)} = (B + E)\omega^{(i)} = B\omega^{(i)} + E\omega^{(i)}, \quad i = 1, 2, \dots, k + p$$

where p is a small number

Randomized Matrix Interpolative Decomposition

Algorithm 4 Randomized matrix interpolative decomposition

Input: An $m \times n$ matrix A and integer $l > k$

Output: Indices set \mathcal{L}_k of the k columns, the permutation matrix P , and the column subset matrix A_{CS}

- 1: Draw an $n \times l$ Gaussian random matrix, Ω .
 - 2: Form $m \times l$ matrix $Y = A\Omega$.
 - 3: Construct an $m \times k$ orthonormal matrix Q for approximate the range of Y via the QR factorization, $Y = QR$.
 - 4: Construct \mathcal{L}_k , P , and A_{CS} from the QR of Y .
-

Randomized Tensor Interpolative Decomposition

Tensor notation:

$$\mathcal{U} = \sum_{l=1}^{\kappa_{\mathcal{U}}} \bigotimes_{j=1}^d \mathbf{u}_j^{(l)} = \sum_{l=1}^{\kappa_{\mathcal{U}}} \mathcal{U}^{(l)}, \quad \mathcal{U}^{(l)} = \bigotimes_{j=1}^d \mathbf{u}_j^{(l)}.$$

where $\mathbf{u}^j \in \mathbb{R}^{M_j}$ for $j = 1, \dots, d$ and $\kappa_{\mathcal{U}}$ is the rank

A matricized tensor U :

$$U = \begin{bmatrix} \left| \begin{array}{c} \mathcal{U}^{(1)} \\ \vdots \end{array} \right. & \dots & \left| \begin{array}{c} \mathcal{U}^{(\kappa_{\mathcal{U}})} \\ \vdots \end{array} \right. \end{bmatrix}$$

The inner product between two tensors \mathcal{U} and \mathcal{V} :

$$\langle \mathcal{U}, \mathcal{V} \rangle = \sum_{l=1}^{\kappa_{\mathcal{U}}} \sum_{m=1}^{\kappa_{\mathcal{V}}} \prod_{j=1}^d \langle \mathbf{u}_j^{(l)}, \mathbf{v}_j^{(m)} \rangle$$

Randomized Tensor Interpolative Decomposition

Algorithm 5 Randomized tensor interpolative decomposition

Input: A rank κ' tensor \mathcal{U} and integer $l > \kappa$

Output: A rank κ tensor $\tilde{\mathcal{U}}$

- 1: Draw a random tensor \mathcal{R} of rank l .
 - 2: Form $l \times \kappa'$ matrix $Y = \mathcal{R}^T \mathcal{U}$.
 - 3: Compute an ID of Y and, as a result, a $\kappa \times \kappa'$ permutation matrix P , and a column index set \mathcal{L}_κ .
 - 4: Compute $\tilde{\mathcal{U}}^{(l)} = \sum_{m=1}^{\kappa'} P_{m|} \mathcal{U}^{(l_m)}$ where $l_m \in \mathcal{L}_\kappa$
-

Active subspace methods

A general multivariate function $f : \mathbb{R}^m \mapsto \mathbb{R}$

$$f = f(\xi), \quad \xi \in \mathbb{R}^m$$

Active subspace method

- 1 Compute the gradient of f :

$$\nabla_{\xi} f(\xi) = \left[\frac{\partial f}{\partial \xi_1}, \dots, \frac{\partial f}{\partial \xi_m} \right]^T$$

- 2 Construct a covariance matrix C :

$$C = \mathbb{E} [(\nabla_{\xi} f(\xi))(\nabla_{\xi} f(\xi))^T]$$

- 3 Compute an eigendecomposition of C :

$$C = W\Lambda W^T, \quad \Lambda = \text{diag}(\lambda_1, \dots, \lambda_m),$$

where $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_m$

- 4 Partition W and Λ :

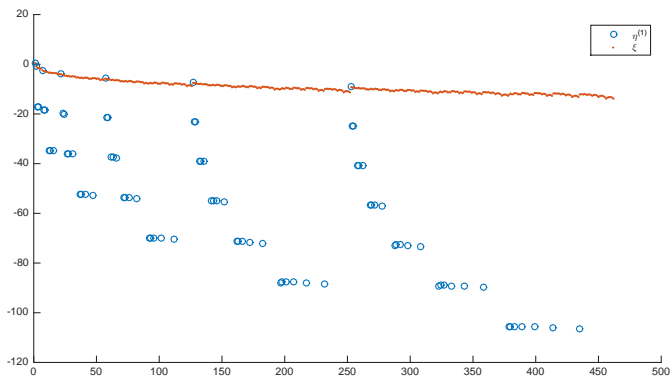
$$\Lambda = \begin{bmatrix} \Lambda_1 & \\ & \Lambda_2 \end{bmatrix}, \quad W = [W_1, W_2]$$

where $\Lambda_1 = \text{diag}(\lambda_1, \dots, \lambda_n)$ with $n < m$ and $W_1 \in \mathbb{R}^{m \times n}$

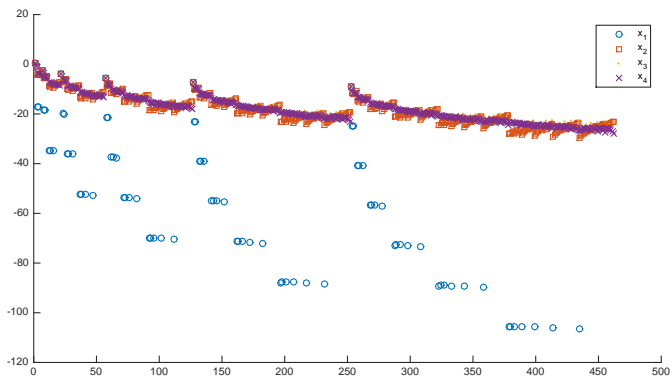
- 5 Rotate ξ :

$$y = W_1^T \xi, \quad z = W_2^T \xi$$

where $y \in \mathbb{R}^n$ and $z \in \mathbb{R}^{m-n}$



At spatial point x_1 , $\log_{10}(|a_\alpha(x_1)|)$ v.s. $\log_{10}(|\hat{a}_\alpha(x_1)|)$



At spatial points x_i , $i = 1, 2, 3, 4$, $\log_{10}(|\hat{a}_\alpha(x_i, \eta^{(1)})|)$

Group n_{set} sets of spatial points

Construct the Jacobian of $a(\mathbf{x}, \xi)$ at a set of spatial points

$\mathbf{x}^{(k)} = \{x_i^{(k)}\}_{i=1}^{n'_x}$, $n'_x = n_x/n_{\text{set}}$ and $k = \{1, \dots, n_{\text{set}}\}$:

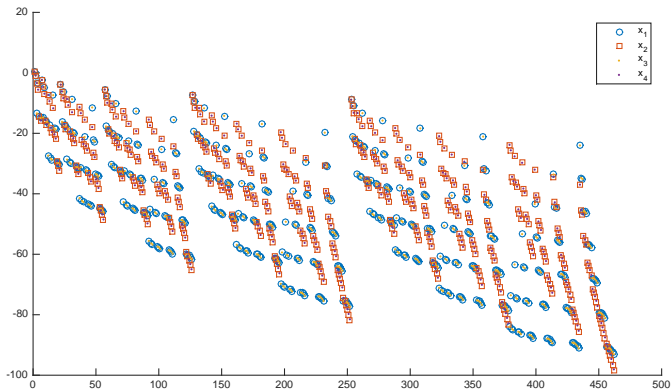
$$J(\mathbf{x}^{(k)}) = \begin{bmatrix} \frac{\partial a(x_1^{(k)}, \xi)}{\partial \xi_1} & \dots & \frac{\partial a(x_{n'_x}^{(k)}, \xi)}{\partial \xi_1} \\ \vdots & & \vdots \\ \frac{\partial a(x_1^{(k)}, \xi)}{\partial \xi_M} & \dots & \frac{\partial a(x_{n'_x}^{(k)}, \xi)}{\partial \xi_M} \end{bmatrix}$$

Compute the covariance matrix:

$$C(\mathbf{x}^{(k)}) = \mathbb{E} \left[J(\mathbf{x}^{(k)}) J(\mathbf{x}^{(k)})^T \right].$$

Rotate ξ :

$$\eta^{\mathbf{x}^{(k)}} = W_{\mathbf{x}^{(k)}}^T \xi \in \mathbb{R}^{M \times 1}$$



At spatial points x_i , $i = 1, 2, 3, 4$, $\log_{10}(|\hat{a}_\alpha(x_i, \eta^{\mathbf{x}^{(1)}})|)$