

Math 225, Fall 2025

Quiz #9

Name: _____

Find the general solution of $\vec{x}' = A\vec{x}$, where $A = \begin{bmatrix} 4 & -6 \\ 1 & -1 \end{bmatrix}$.

Solution: [Like Exercises 10–15 of section 6.4]

We begin with solving the eigenvalue problem $A\vec{\zeta} = \lambda\vec{\zeta}$. The eigenvalues are solution to the algebraic equation $\det(A - \lambda I) = 0$. We have

$$A - \lambda I = \begin{bmatrix} 4 - \lambda & -6 \\ 1 & -1 - \lambda \end{bmatrix},$$

and therefore

$$\begin{aligned} \det(A - \lambda I) &= (4 - \lambda)(-1 - \lambda) + 6 \\ &= -4 - 4\lambda + \lambda + \lambda^2 + 6 = \lambda^2 - 3\lambda + 2 = (\lambda - 1)(\lambda - 2). \end{aligned}$$

We conclude that the eigenvalues are $\lambda_1 = 1$ and $\lambda_2 = 2$. Next, we calculate the corresponding eigenvectors, $\vec{\zeta}^{(1)}$ and $\vec{\zeta}^{(2)}$ by solving $(A - \lambda_1 I)\vec{\zeta}^{(1)} = \vec{0}$ and $(A - \lambda_2 I)\vec{\zeta}^{(2)} = \vec{0}$.

We have

$$A - \lambda_1 I = \begin{bmatrix} 4 - \lambda_1 & -6 \\ 1 & -1 - \lambda_1 \end{bmatrix} = \begin{bmatrix} 3 & -6 \\ 1 & -2 \end{bmatrix},$$

and therefore $(A - \lambda_1 I)\vec{\zeta}^{(1)} = \vec{0}$ takes the form

$$\begin{bmatrix} 3 & -6 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} \zeta_1 \\ \zeta_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

which amounts to $\zeta_1 = 2\zeta_2$. We pick $\zeta_2 = 1$, $\zeta_1 = 2$ for the solution and arrive at

$$\vec{\zeta}^{(1)} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}.$$

Similarly, we have

$$A - \lambda_2 I = \begin{bmatrix} 4 - \lambda_2 & -6 \\ 1 & -1 - \lambda_2 \end{bmatrix} = \begin{bmatrix} 2 & -6 \\ 1 & -3 \end{bmatrix},$$

and therefore $(A - \lambda_2 I)\vec{\zeta}^{(2)} = \vec{0}$ takes the form

$$\begin{bmatrix} 2 & -6 \\ 1 & -3 \end{bmatrix} \begin{bmatrix} \zeta_1 \\ \zeta_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

which amounts to $\zeta_1 = 3\zeta_2$. We pick $\zeta_2 = 1$, $\zeta_1 = 3$ for the solution and arrive at

$$\vec{\zeta}^{(2)} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}.$$

Then, the DE's general solution, that is, $\vec{x}(t) = c_1 e^{\lambda_1 t} \vec{\zeta}^{(1)} + c_2 e^{\lambda_2 t} \vec{\zeta}^{(2)}$, takes the form

$$\vec{x}(t) = c_1 e^t \begin{bmatrix} 2 \\ 1 \end{bmatrix} + c_2 e^{2t} \begin{bmatrix} 3 \\ 1 \end{bmatrix}.$$