

CMSC 341

Lecture 20 Disjointed Sets

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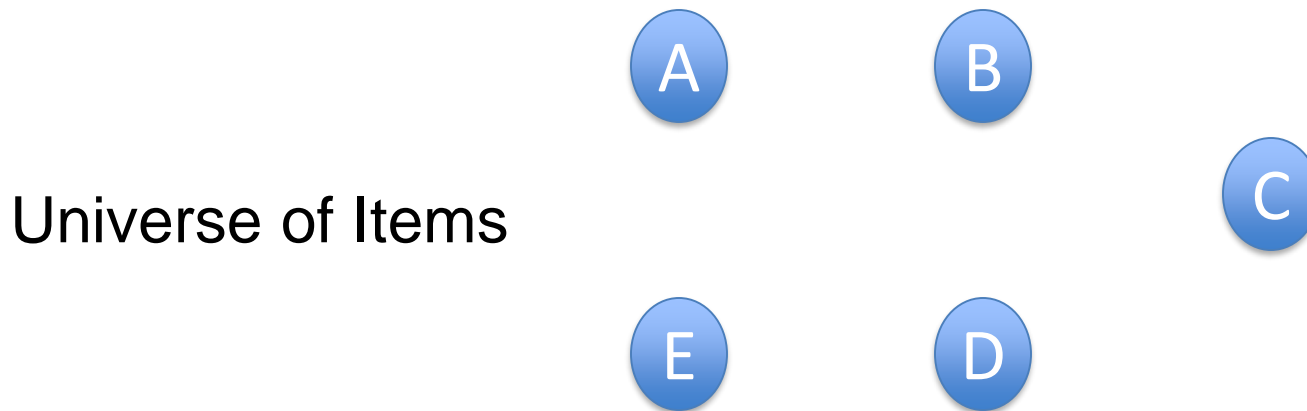
Introduction to Disjointed Sets

Disjoint Sets

- A data structure that keeps track of a set of elements partitioned into a number of disjoint (non-overlapping) subsets

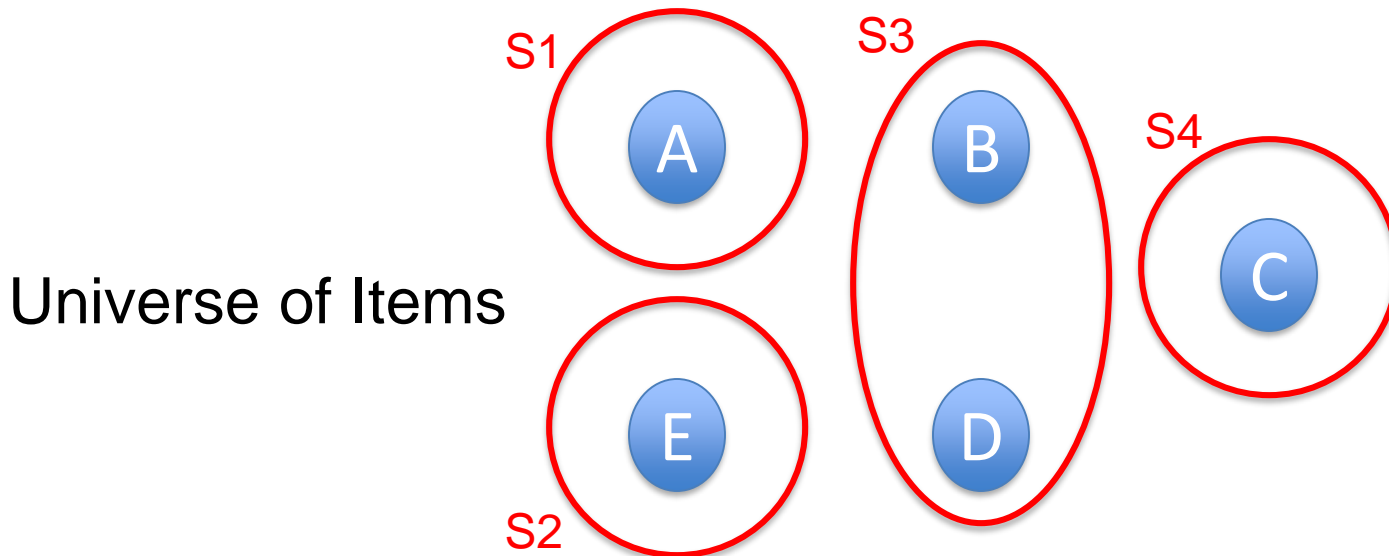
Universe of Items

- Universal set is made up of all of the items that can be a member of a set



Disjoint Sets

- A group of sets where no item can be in more than one set



Disjoint Sets

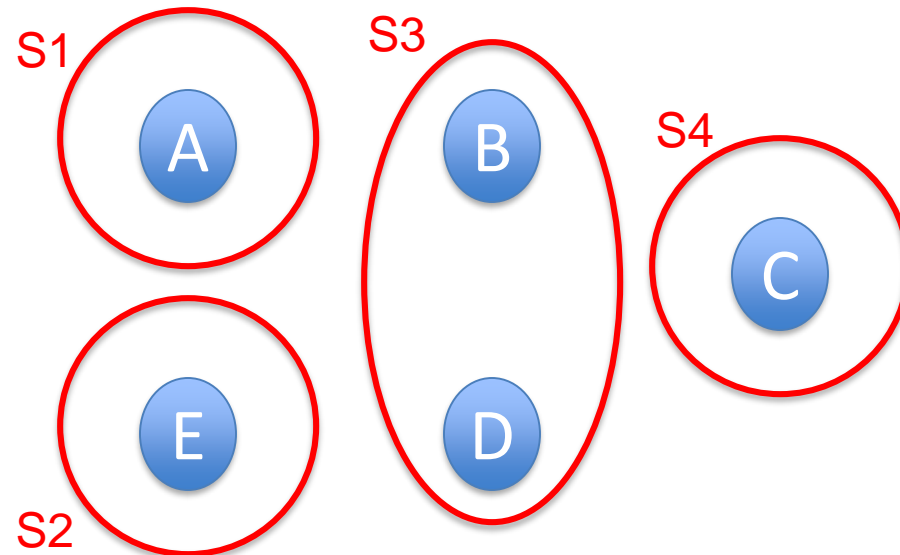
- A group of sets where no item can be in more than one set

Supported Operations:

Find()

Union()

MakeSet()

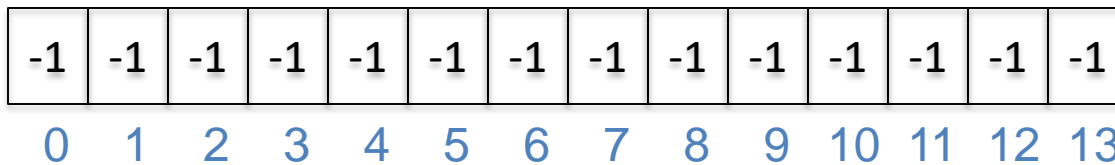


Uses for Disjointed Sets

- Maze generation
- Kruskal's algorithm for computing the minimum spanning tree of a graph
 - Given a set of cities, C , and a set of roads, R , that connect two cities (x, y) determine if it's possible to travel from any given city to another given city
- **Determining if there are cycles in a graph**

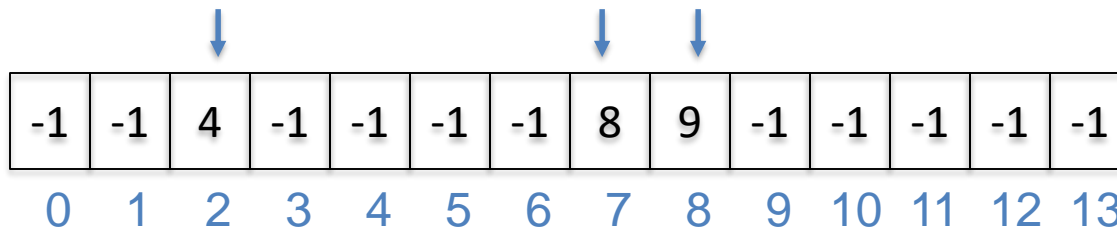
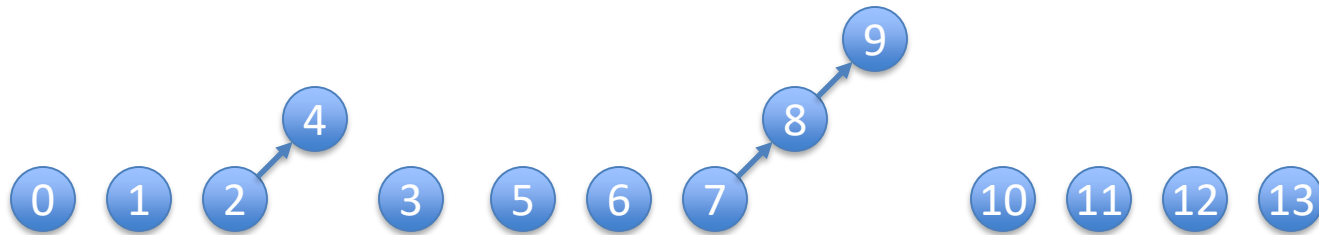
Disjoint Set Example

Disjoint Set with No Unions



- A negative number means we are at the root
- A positive number means we need to move or “walk” to that index to find our root
- The LONGER the path, the longer it takes to find, and moves farther away from our goal of a constant timed function

Disjoint Set with Some Unions



Notice:

- Value of index is where the index is linked to

Operations of a Disjoint Set

Find()

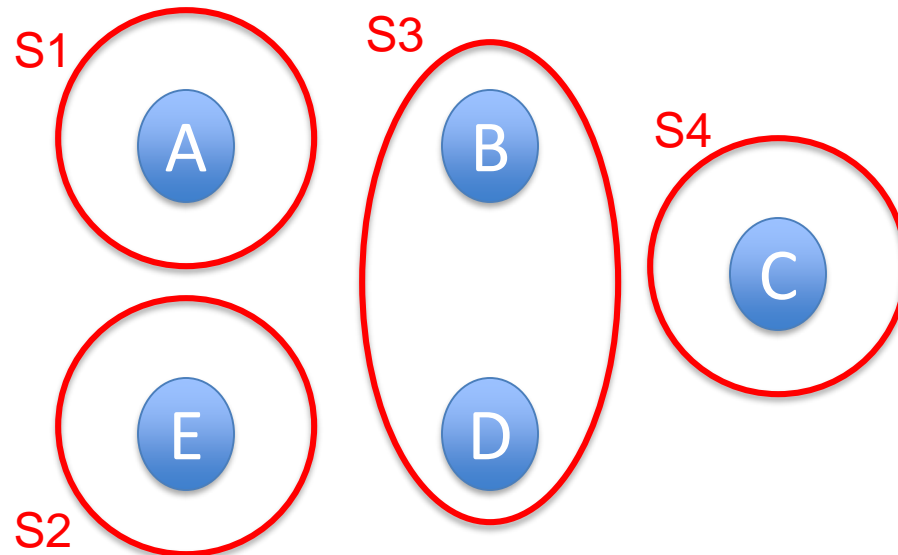
- Determine which subset an element is in
- Returns the name of the subset
- **Find()** typically returns an item from this set that serves as its "representative"
 - By comparing the result of two **Find()** operations, one can determine whether two elements are in the same subset

Find()

- Asks the question, what set does item E belong to currently?

What does
Find(E) return?

Returns S2

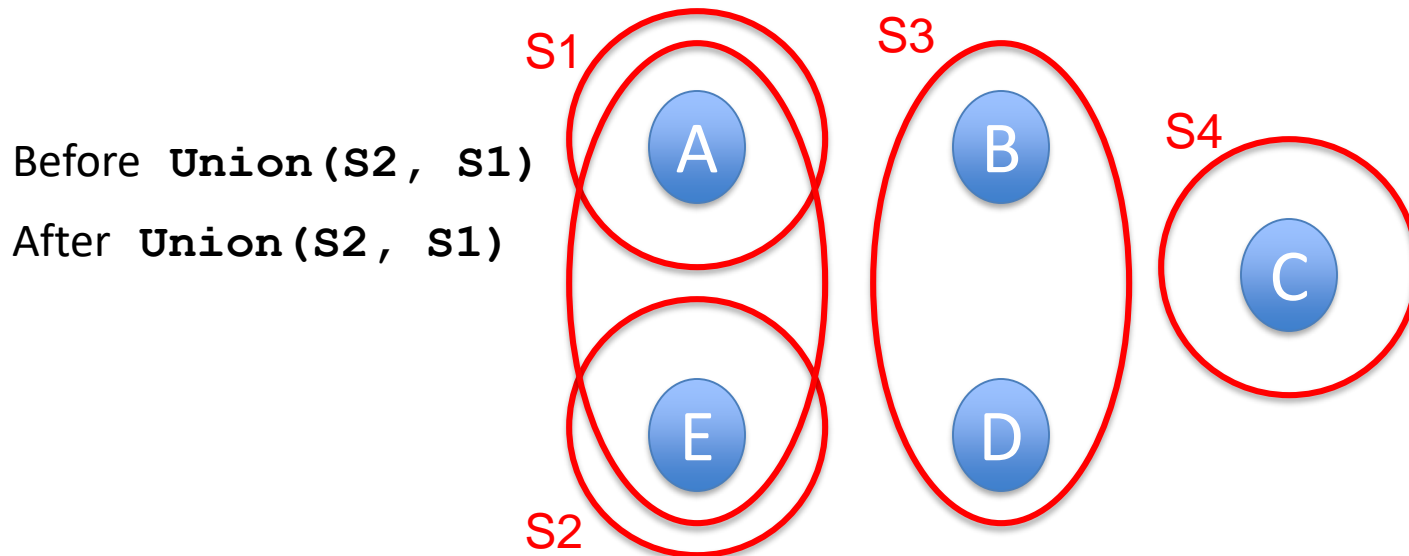


Union ()

- **Union ()**
 - Merge two sets (w/ one or more items) together
 - Order can be important
 - One of the roots from the 2 sets will become the root of the merged set

Union ()

- Join two subsets into a single subset.



MakeSet ()

- Makes a set containing only a given element (a singleton)
- Implementation is generally trivial

Types of Disjoint Sets

Types of Disjoint Sets

- There are two types of disjoint sets
 1. Array Based Disjoint Sets
 2. Tree Based Disjoint Sets
 - (We can also implement with a linked list)

Array Based Disjoint Sets

- We will assume that elements are 0 to $n - 1$
- Maintain an array **A**: for each element **i**, **A[i]** is the name of the set containing **i**

Array Based Disjoint Sets

- **Find(i)** returns **A[i]**
 - Runs in $O(1)$
- **Union(i, j)** requires scanning entire array
 - Runs in $O(n)$

```
for (k = 0; k < n; k++) {  
    if (A[k] == A[j]) {  
        A[k] = A[i]; } }  
}
```

Tree Based Disjoint Sets

- Disjoint-set forests are data structures
 - Each set is represented by a tree data structure
 - Each node holds a reference to its parent node
- In a disjoint-set forest, the representative of each set is the root of that set's tree

Tree Based Disjoint Sets

- **Find()** follows parent nodes until it reaches the root
- **Union()** combines two trees into one by attaching the root of one to the root of the other

Animation

- Disjoint Sets
- <https://www.cs.usfca.edu/~galles/visualization/DisjointSets.html>

Optimization of Disjointed Sets

Optimization

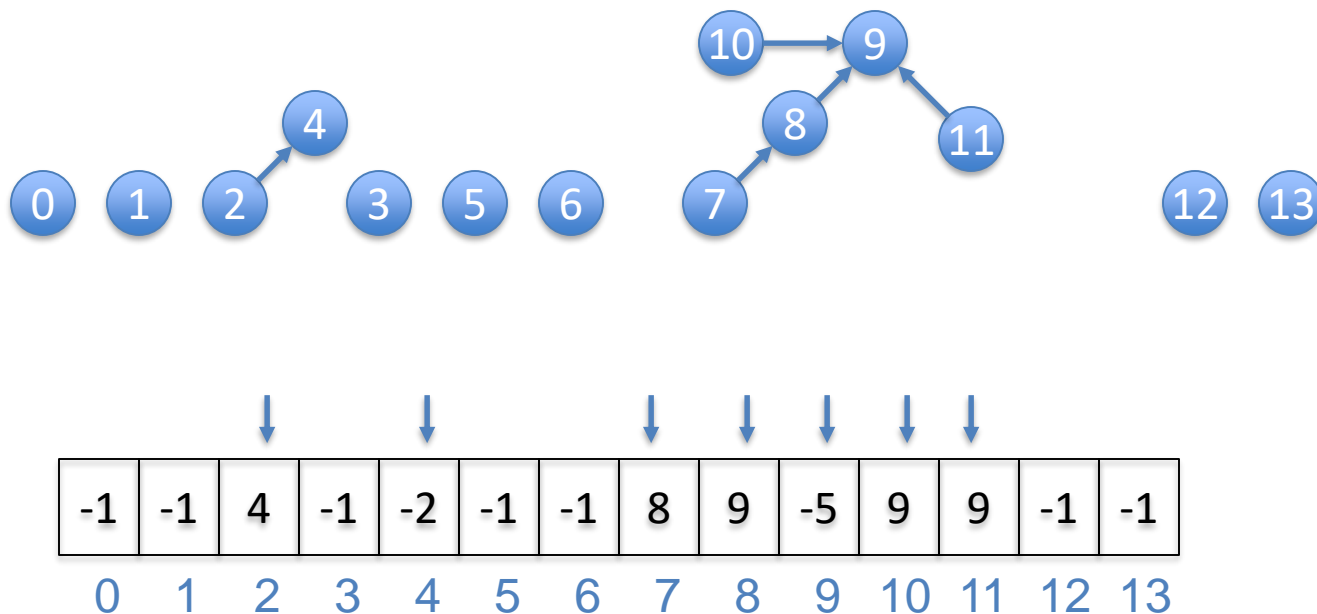
- Three main optimization operations:
 1. Union-by-rank (size)
 2. Union-by-rank (height)
 3. Path Compression

- Be very clear about how the array representations change for different things (union by size, union by height, etc.)

Union-by-Rank (size)

- *Size* = number of nodes (including root) in given set
- A strategy to keep items in a tree from getting too deep (large paths) by uniting sets intelligently
- At each root, we record the *size* of its sub-tree
 - The number of nodes in the collective tree

Union-by-Rank (size)



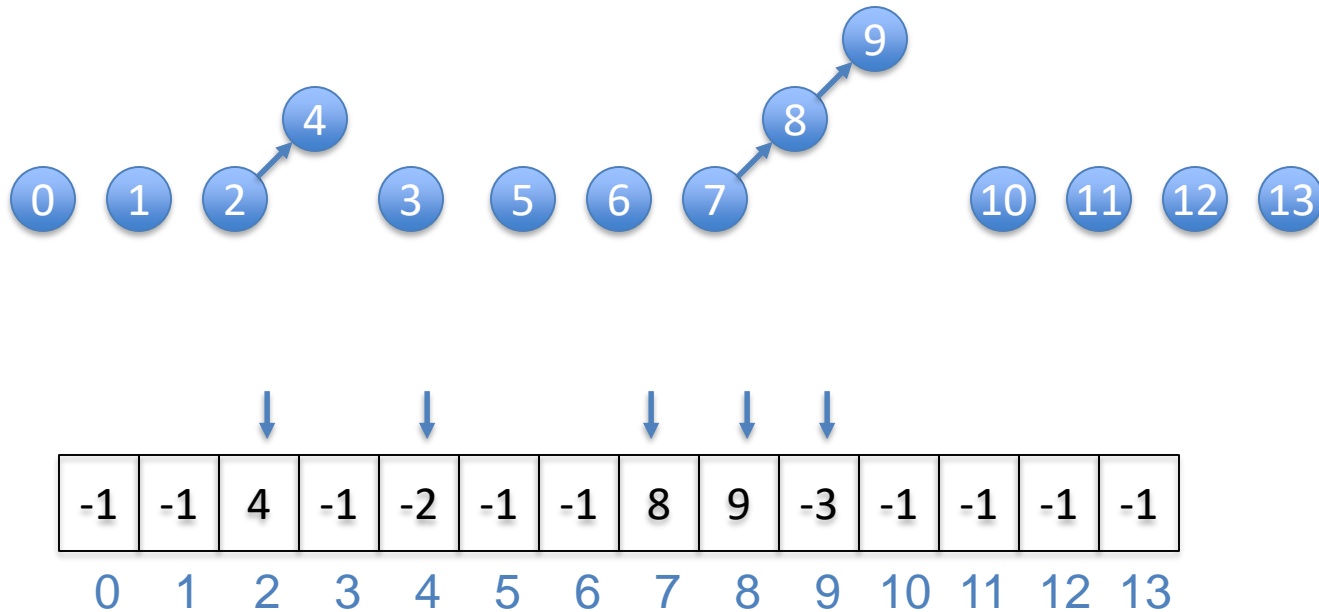
Notice two things:

1. Value of index is where the index is linked to
2. As the size of the set increases, the negative number **size** of the root increases (see 4 and 9)

Union-by-Rank (height)

- A strategy to keep items in a tree from getting too deep (large paths) by uniting sets intelligently
- At each root, we record the *height* of its sub-tree
- When uniting two trees, make the smaller tree a sub-tree of the larger one
 - So that the tree that is larger does not add **another** level!!

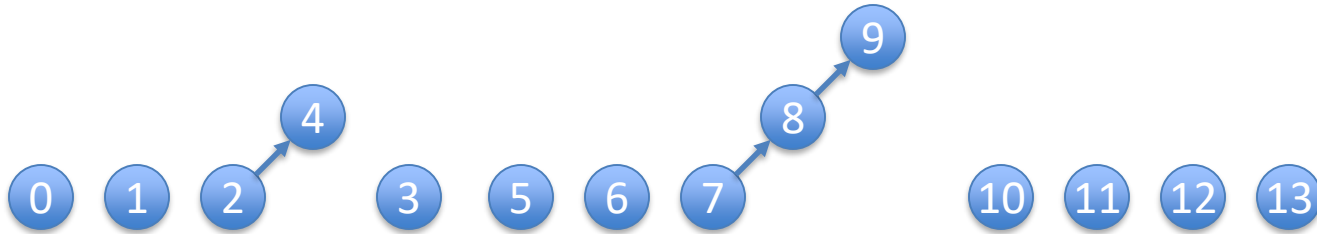
Union-by-Rank (height)



Notice two things:

1. Value of index is where the index is linked to
2. As the size of the set increases, the negative number **height** of the root increases (see 4 and 9)

Union-by-Rank (height)

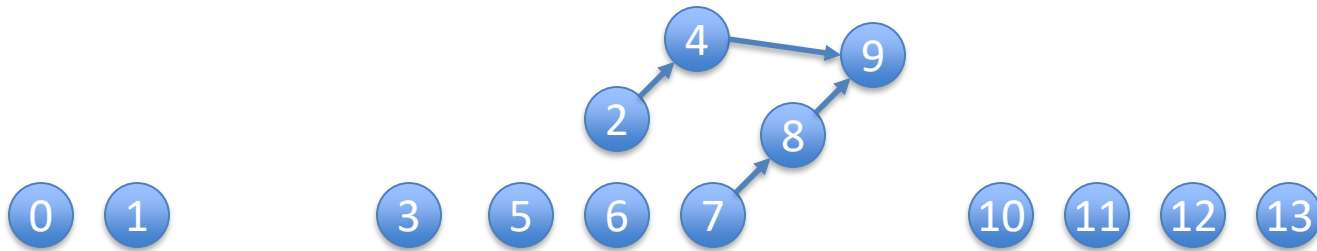


-1	-1	4	-1	-2	-1	-1	8	9	-3	-1	-1	-1	-1
0	1	2	3	4	5	6	7	8	9	10	11	12	13

What if we merge $\{2,4\}$ with $\{7, 8, 9\}$?

Because 9 has a greater height than 4, 4 would be absorbed into 9.

Union-by-Rank (height)



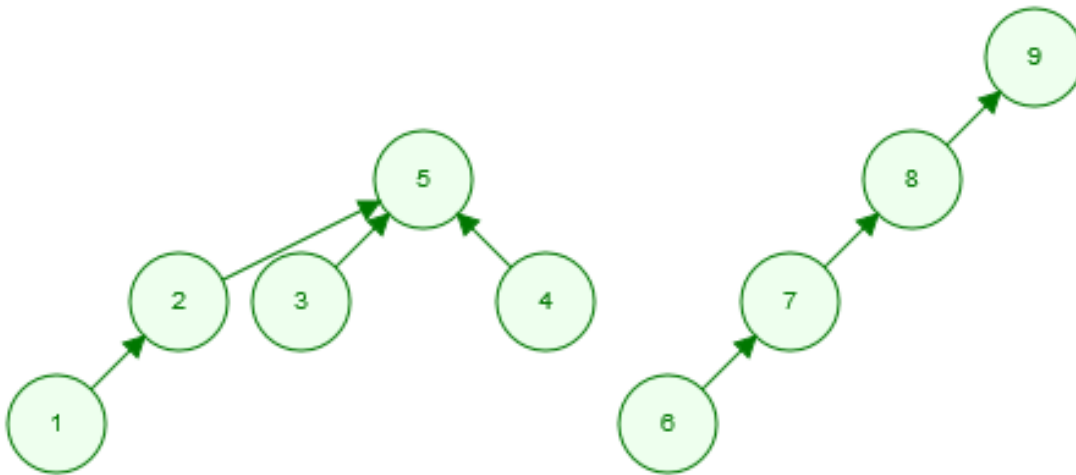
Update 4 to point to 9

-1	-1	4	-1	2	-1	-1	8	9	-3	-1	-1	-1	-1
0	1	2	3	4	5	6	7	8	9	10	11	12	13

When uniting two trees, make the smaller tree a sub-tree of the larger one so that the one tree that is larger does not add **another** level!!

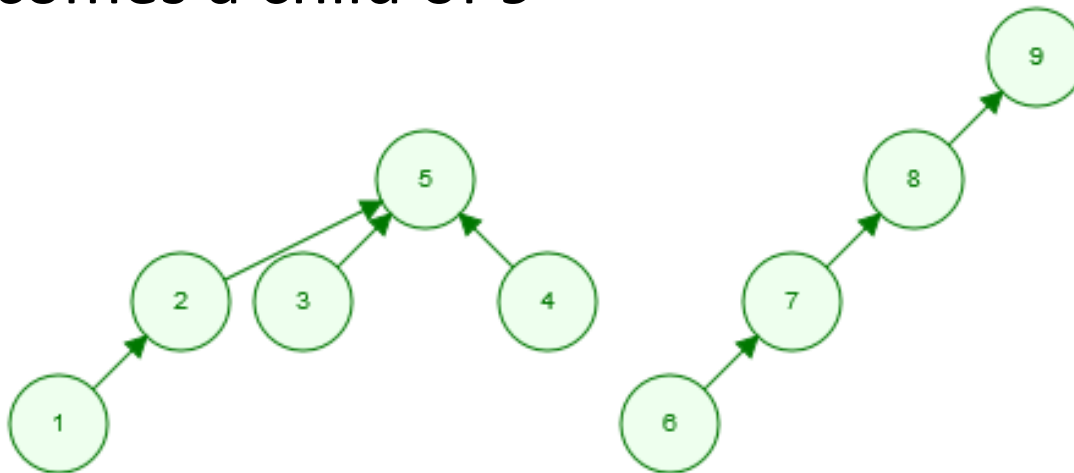
Example of Unions

- If we union 5 and 9, how will they be joined?



Example of Unions

- By rank (size)?
 - 9 becomes a child of 5
- By rank (height)?
 - 5 becomes a child of 9



Path Compression

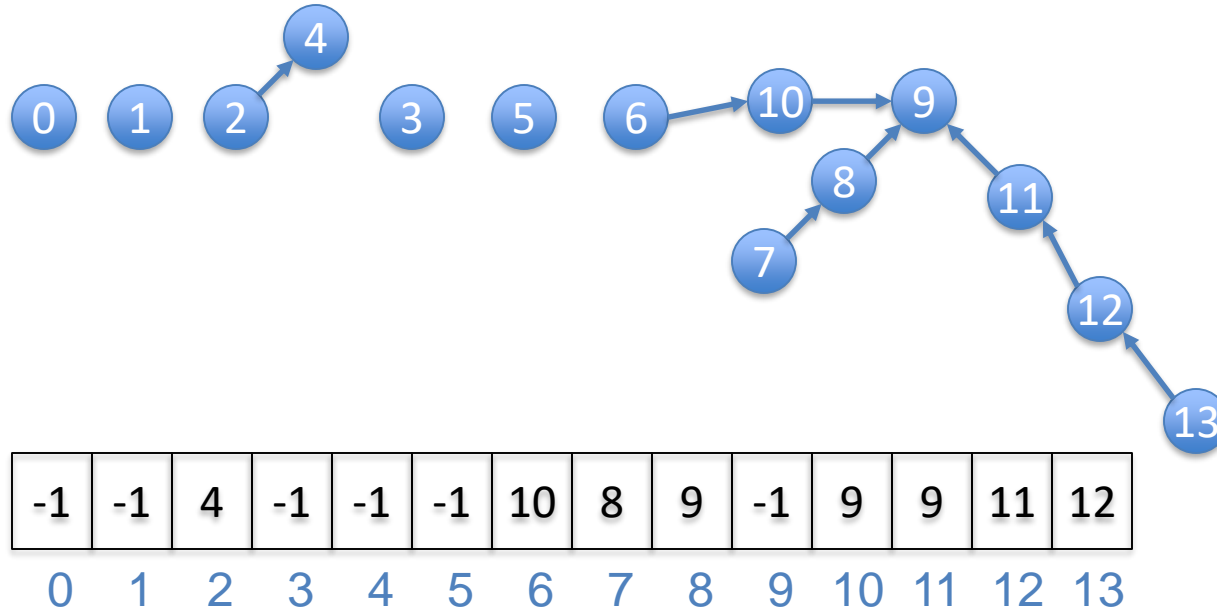
- If our path gets longer, operations take longer
- We can shorten this (literally and figuratively) by updating the element values of each child directly to the root node value
 - No more walking through to get to the root
- Done as part of **Find()**
 - So the speed up will be eventual

Path Compression

- Theoretically flattens out a tree
- Uses recursion
- Base case
 - Until you find the root
 - Return the root value
- Reassign as the call stack collapses

Path Compression

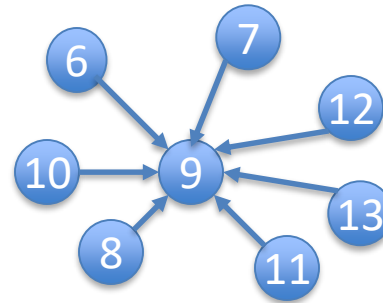
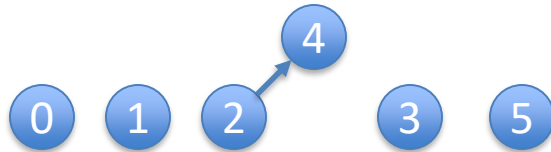
Before Path Compression



During a `Find()`, we update the index to point to the root

Path Compression

After Path
Compression



-1	-1	4	-1	-1	-1	9	9	9	-1	9	9	9	9
0	1	2	3	4	5	6	7	8	9	10	11	12	13

After we run `Find(6)` we update it to point to 9

After we run `Find(13)` we update it to point to 9

Along with all other nodes between 13 and 9!

Code for Disjoint Sets

Generic Code

```
function MakeSet(x)
    x.parent := x
```

```
function Find(x)
    if x.parent == x
        return x
    else
        return Find(x.parent)
```

```
function Union(x, y)
    xRoot := Find(x)
    yRoot := Find(y)
    xRoot.parent := yRoot
```


C++ Implementation

```
class UnionFind {
    int[] u;

    UnionFind(int n) {
        u = new int[n];
        for (int i = 0; i < n; i++)
            u[i] = -1;
    }

    int find(int i) {
        int j, root;
        for (j = i; u[j] >= 0; j = u[j]) ;
        root = j;
        while (u[i] >= 0) { j = u[i]; u[i] = root; i = j; }
        return root;
    }

    void union(int i, int j) {
        i = find(i);
        j = find(j);
        if (i != j) {
            if (u[i] < u[j])
                { u[i] += u[j]; u[j] = i; }
            else
                { u[j] += u[i]; u[i] = j; }
        }
    }
}
```

The UnionFind class

```
class UnionFind {
    int[] u;

    UnionFind(int n) {
        u = new int[n];
        for (int i = 0; i < n; i++)
            u[i] = -1;
    }

    int find(int i) { ... }

    void union(int i, int j) { ... }
}
```

Trick 1: Iterative find

```
int find(int i) {  
    int j, root;  
  
    for (j = i; u[j] >= 0; j = u[j]) ;  
    root = j;  
  
    while (u[i] >= 0)  
        { j = u[i]; u[i] = root; i = j; }  
  
    return root;  
}
```

Trick 2: Union by size

```
void union(int i,int j) {  
    i = find(i);  
    j = find(j);  
  
    if (i != j) {  
        if (u[i] < u[j])  
            { u[i] += u[j]; u[j] = i; }  
        else  
            { u[j] += u[i]; u[i] = j; }  
    }  
}
```

Disjointed Sets Performance

Performance

- In a nutshell
 - Running time complexity: $O(1)$ for union
 - Using ONE pointer to connect from one root to another
 - Running time of find depends on implementation
 - Union by size: Find is $O(\log(n))$
 - Union by height: Find is $O(\log(n))$
- Union operations obviously take $\Theta(1)$ time
 - Code has no loops or recursion
 - $\Theta(f(n))$ is when the worst case and best case are identical

Performance

- The *average running* time of any find and union operations in the quick-union data structure is so close to a constant that it's hardly worth mentioning that, in an asymptotic sense, it's *slightly* slower in real life

Performance

- A sequence of f find and u union operations (in any order and possibly interleaved) takes $\Theta(u + f \alpha(f + u, u))$ time in the worst case
- α is an extremely slowly-growing function
- Known as the inverse ***Ackermann function***.
 - This function is never larger than 4 for any values of f and u you could ever use (though it can get arbitrarily large—for unimaginably large values of f and u).
 - Hence, for all practical purposes think of quick-union as having find operations that run, on average, in constant time.