

Name:

SOLUTION.

Date:

PHYS 224 - Introductory Physics III

Mid-Term Exam 1

P₁) 1.1)

$$a) \omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{80}{1}}$$

$$\omega = 8.94 \text{ rad/s} //$$

$$T = \frac{2\pi}{\omega} \Rightarrow T = 0.702 \text{ s} //$$

$$f = 1/T = 1.424 \text{ Hz} //$$

$$b) \omega = \sqrt{\frac{mg}{l}} = \sqrt{\frac{9.8}{0.5}}$$

$$\omega = 4.43 \text{ rad/s} //$$

$$T = 1.42 \text{ s} //$$

$$f = 0.704 \text{ Hz}$$

$$c) \omega = \sqrt{\frac{\rho A g}{m}}$$

$$\omega = \sqrt{\frac{0.9 \pi \cdot 0.2^2 \cdot 9.8}{1}}$$

$$\omega = 1.05 \text{ rad/s} //$$

$$T = 5.97 \text{ s} //$$

$$f = 0.167 \text{ Hz.}$$

1.2)

$$a) \omega_{\text{new}} = \sqrt{\frac{80}{2}} = 6.32 \frac{\text{rad}}{\text{s}}$$

$$T_{\text{new}} = 0.993 \text{ s} //$$

b)

$$\omega_{\text{new}} = \omega$$

$$T_{\text{new}} = 1.42 \text{ s} //$$

$$c) \omega_{\text{new}} = \sqrt{\frac{\rho A g}{2m}}$$

$$\omega_{\text{new}} = 0.744 \text{ rad/s}$$

$$T_{\text{new}} = 8.44 \text{ s} //$$

1.3)

$$a) F = k \cdot x$$

$\therefore k$ does not depend on the mass ///

$$k_m = k_{2m} = 80 \text{ N/m} //$$

$$b) F = \frac{m \cdot g}{l} \cdot x$$

$$\Rightarrow k = \frac{m \cdot g}{l} = \frac{1 \cdot 9.8}{0.5}$$

$$k_m = 19.6 \text{ N/m} //$$

$$k_{2m} = 39.2 \text{ N/m} //$$

$$c) F = \rho A g \cdot y.$$

$$k = \rho A g$$

$\therefore k$ does not depend on m .

$$k_m = k_{2m} = 1.11 \frac{\text{N}}{\text{m}} //$$

- 2.1) a) simple harmonic motion
 b) beat
 c) damped harmonic motion

2.2) $A_0 = 0.30 \text{ m}$

$$\omega_0 = \sqrt{\frac{k}{m}} = \sqrt{\frac{30}{0.2}} = 12.25 \text{ rad/s} //$$

2.3) $\omega_{\text{motion}} = \frac{\omega_0 + \omega_2}{2} = \frac{12.25 + 1.1 \times 12.25}{2} = 12.86 \frac{\text{rad}}{\text{s}} //$

$$\omega_{\text{beat}} = \frac{\omega_2 - \omega_0}{2} = \frac{1.1 \times 12.25 - 12.25}{2} = 0.612 \frac{\text{rad}}{\text{s}} //$$

$$f_{\text{motion}} = \frac{\omega_{\text{motion}}}{2\pi} = \frac{12.86}{2\pi} = 2.047 \text{ Hz} //$$

$$f_{\text{beat}} = \frac{\omega_{\text{beat}}}{2\pi} \cdot 2 = \frac{0.612}{2\pi} \cdot 2 = 0.195 \text{ Hz} //$$

$$T_{\text{motion}} = \frac{1}{f_{\text{motion}}} = 0.489 \text{ s} //$$

$$T_{\text{beat}} = \frac{1}{f_{\text{beat}}} = 5.13 \text{ s} //$$

2.4) $b = 1.0 \text{ kg/s}$

$$\omega^2 = \left(\omega_0^2 - \frac{b^2}{4m^2} \right) = \left(12.25^2 - \frac{1^2}{4 \cdot 0.2^2} \right) \Rightarrow \omega = 11.99 \frac{\text{rad}}{\text{s}}$$

$$f = \frac{\omega}{2\pi} = 1.91 \text{ Hz} // \quad T = \frac{1}{f} = 0.524 \text{ s} //$$

2.5) Critically Damped System $\Rightarrow \omega_0^2 = \frac{b^2}{4m^2} \Rightarrow b = \sqrt{4m^2\omega_0^2}$

$$\Rightarrow b = 2m\omega_0 = 4.90 \text{ kg/s}$$

The system will not oscillate. It will decay fast to the equilibrium position without any overshoot.

2.6) Overdamped system $\Rightarrow \omega_0^2 - \frac{b^2}{4m^2} < 0 \Rightarrow \boxed{b > 2m\omega_0}$

Solution $z = A e^{-\frac{\gamma}{2}t} e^{j(\omega t + \phi)}$

$$\omega^2 = \omega_0^2 - \frac{b^2}{4m^2} \quad \text{for } b > 2m\omega_0 \Rightarrow \omega^2 < 0$$

$$\Rightarrow \omega = \pm j\beta \quad \text{where } \beta = \left(\frac{\gamma^2}{4} - \omega_0^2\right)^{1/2}$$

Substituting back in the solution:

$$z = A e^{-\gamma/2 t} e^{j(\pm j\beta t + \phi)} = A e^{-\gamma/2 t} e^{\mp \beta t + j\phi}$$

$$z = A e^{-(\gamma/2 \pm \beta)t + j\phi}$$

$\therefore \boxed{x = \text{Re}(z) = A e^{-(\gamma/2 \pm \beta)t}}$ Which has no oscillatory component.
Only exponential decay.///

P3) case a) $E = K + U = \frac{1}{2} m v^2 + \frac{1}{2} k x^2 = \text{const}$
 Since there is no damping or forcing in the system.

$$\text{For } v=0 \Rightarrow x=A \Rightarrow E = \frac{1}{2} k A^2 = \frac{1}{2} 80 \cdot 0.3^2 = 3.6 \text{ J}$$



case b) System has damping: $A = A_0 e^{-\frac{\gamma}{2} t}$

$$E = \frac{1}{2} k A^2 = \underbrace{\frac{1}{2} k A_0^2}_{E_0} e^{-\frac{\gamma}{2} t} = 3.6 e^{-\gamma t}$$



In case a) the energy is conserved as a function of time because the system has no damping.

In case b) the mechanical energy of the system decays exponentially due to damping.

$$\textcircled{4} \text{ a) } \frac{d^2 z}{dt^2} + \frac{k}{m} z = \frac{F_0}{m} e^{j\omega t}$$

$$z = A e^{j(\omega t + \phi)}$$

$$\frac{dz}{dt} = A j\omega e^{j(\omega t + \phi)}$$

$$\frac{d^2 z}{dt^2} = -A\omega^2 e^{j(\omega t + \phi)}$$

$$\left(-A\omega^2 + \frac{\omega_0^2}{m} A\right) e^{j(\omega t + \phi)} = \frac{F_0}{m} e^{j\omega t}$$

$$(\omega_0^2 - \omega^2) A = \frac{F_0}{m} \frac{e^{j\omega t}}{e^{j(\omega t + \phi)}} = \frac{F_0}{m} e^{-j\phi}$$

$$\Rightarrow (\omega_0^2 - \omega^2) A = \frac{F_0}{m} \cos\phi - j \frac{F_0}{m} \sin\phi$$

$$\Rightarrow \boxed{A = \frac{F_0}{m(\omega_0^2 - \omega^2)} \cos\phi}$$

$$\text{b) } \omega = 6 \text{ rad/s} \quad F_0 = 2 \text{ N} \quad m = 1 \text{ kg.}$$

$$\omega_0 = \sqrt{\frac{k}{m}} = \sqrt{\frac{80}{1}} = 8.94 \text{ rad/s}$$

$$A = \frac{2}{1(80 - 36)} \underbrace{\cos\phi}_{=1.0} = 0.0455 \text{ m}$$