

Wednesday, 05/02/12:

HW 5, 6, 7 approach:

HW 5 = serial C = lecture today

idea of coding in C is to test everything fully in Matlab
 \Rightarrow lab today = Matlab code

"serial" here: framework of parallel code =
allocations of l_u (not u), use MPI-Whine, Makefile
with `mpicc`, utility functions like `parallel_dot`

but: - run with one process only
- `Ax()` function in serial

HW 6 = parallel C with all performance studies done
and results assembled in tables and plots
also report written

HW 7 = feedback on report, tables, and figures \Rightarrow revision

Start with Matlab so far:

`driver_ge.m` and `driver_cg.m`

(same except for $u = A \setminus b$ vs. $u = \text{pcg}(\dots)$)

`setupA.m` to set up sparse matrix A

\Rightarrow Gauss elimination for sparse matrix A
CG method using sparse matrix A

We see that Gauss runs out of memory for some N value
CG might allow for one more N value

Two reasons for matrix-free implementation now:

- we might be able to solve for a larger N
- since setting up sparse matrix in C is non-trivial, it is actually easier to do matrix-free.

⇒ today: want a third version of Matlab code for CG using matrix-free function `Ax.m`
still use `pcg.m` in Matlab!

What do we need to do/have for C?

CG → download `cg.c` and use it
→ need to read and understand interface

Makefile: `OBJS = cg.o`
`EXECUTABLE = poisson`

Submission script: change its name to `poisson...`
change name to `poisson`
`./poisson N tol maxit`

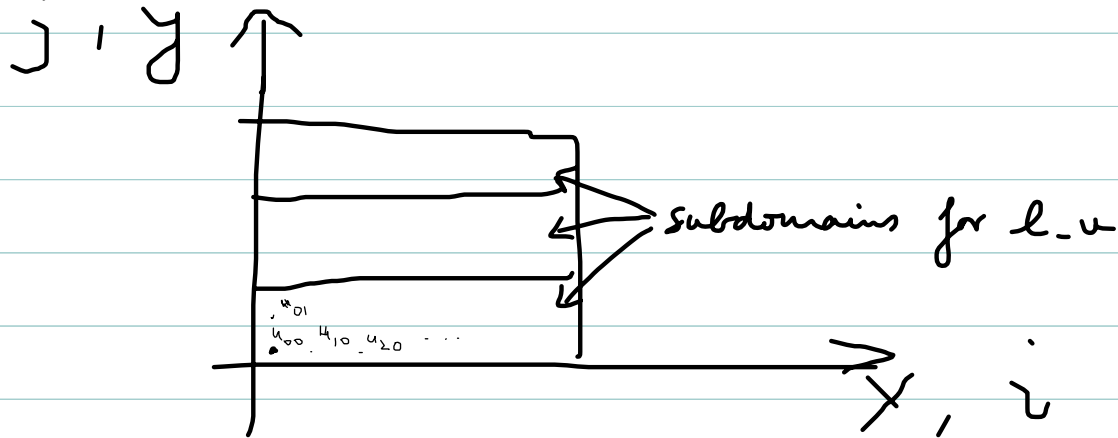
(for simplicity, you can simply use `tol = 10-6` and `maxit = 50,000`)

`main()` program: follow outline of `driver_cg.m`
→ understand interface to `cg()` and supply all needed information

`Ax` function !

We looked through cgl) and noticed several things that we need to supply or set.

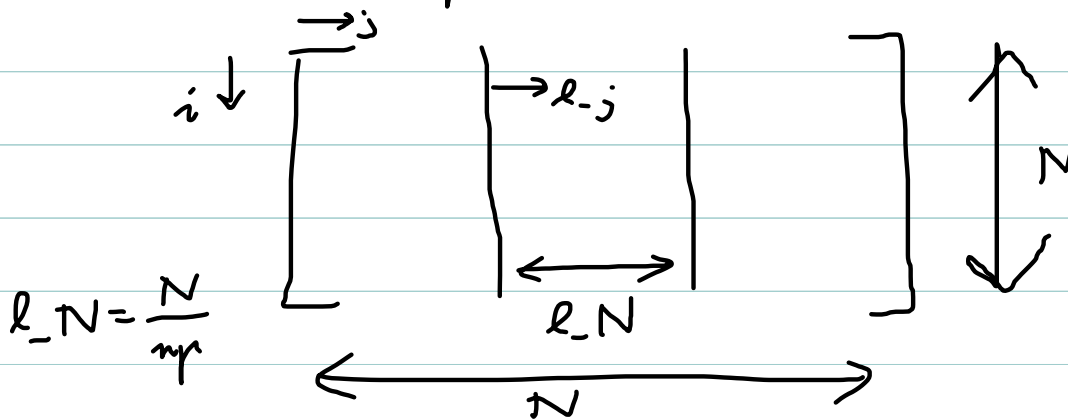
Datastructure:



$$\Leftrightarrow U = (u_{ij}) = \left[\begin{array}{ccc|c|c} u_{00} & u_{10} & \dots & -l_u & l_u \\ u_{10} & & & & \\ u_{20} & & & & \\ \vdots & & & & \end{array} \right]$$

Notice PDE viewpoint with Ω split into subdomains is transpose of matrix viewpoint.

In matrix viewpoints



CG for $Au=b$ has dimension $n = N^2$

and therefore $l_u = \frac{n}{n_p} = N * l_N$

Main program:

$l_u = (\text{double}^*) \text{malloc}(l_n * \text{sizeof}(\text{double}))$

$l_b = \dots$

$l_p = \dots$

$l_f = \dots$

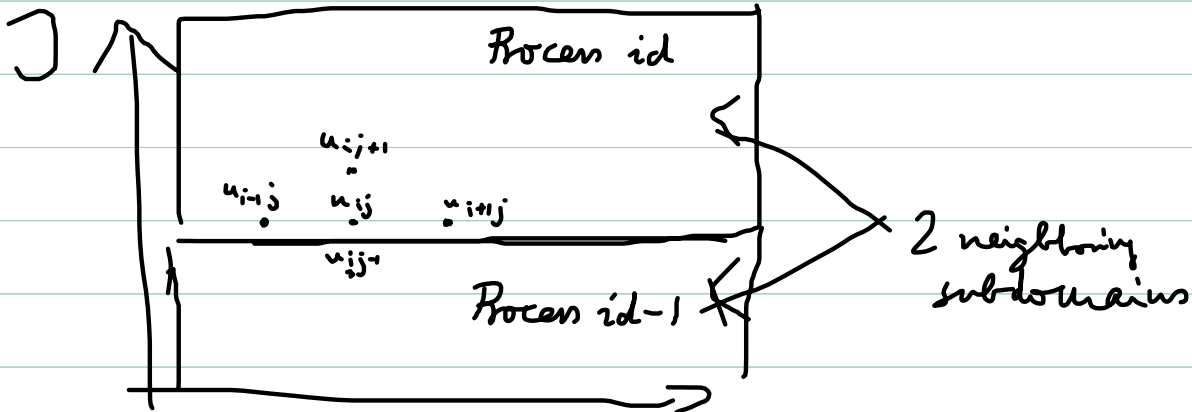
\Rightarrow only exactly 4 vectors of large size $N \times l_n$

$g_l = (\text{double}) \text{malloc}(\underbrace{(l_n / l_n)}_{= N \text{ in 2-D}} * \text{sizeof}(\text{double}))$

$g_r = \dots \dots \dots$

\Leftrightarrow amount of data to communicate between neighboring processes

Understand this from PDE viewpoint of FD stencil



In the computation of $u_{i,j}$ on Proc id, we need data $u_{i-1,j}$, $u_{i+1,j}$, and $u_{i,j+1}$ that is also on Proc id, and $u_{i,j-1}$ that is on Proc id-1

⇒ We need to communicate between neighboring processes, $l_n/l_N = N$ in 2-D double numbers

⇒ gl, gr are vectors to hold the data that is communicated (length l_n/l_N) and we need $idleft = id - 1$ and $idright = id + 1$

More precisely, do this:

```
if ( id > 0 )
    idleft = id - 1
else
    idleft = MPI_PROC_NULL
if ( id < np - 1 )
    idright = id + 1
else
    idright = MPI_PROC_NULL
```

Some ideas on code:

```
h = 1.0 / ((double)(N+1))
x = (double*) malloc ( N * sizeof(double) )
y = ...
for ( i = 0; i < N; i++ ) x[i] = h * ((double)(i+1))
for ( j = ... ) y[j] = ... j+1
for ( l_j = 0; l_j < l_N; l_j++ )
    for ( i = 0; i < N; i++ )
        j = l_j + l_N * id
        p_r[i + N * l_j] = (h*h) * f(x[i], y[j])
```

Heart of a matrix-free code: $Ax()$

Here: serial version!

```
void Ax(double *v, double *u, int l_n,  
        int l_N, int N, int id, int idleft,  
        int idright, int nproc, MPI_Comm comm,  
        double *gl, double *gr)
```

Want to implement: $(i+Nj)$ component of $v=Au$

$$\Leftrightarrow v_{ij} = -u_{i,j-1} - u_{i,j+1} + 4u_{ij} - u_{i+1,j} - u_{i-1,j}$$

in C:

```
double tmp  
int i, j
```

```
for (j=0; j<N; j++) {  
    for (i=0; i<N; i++) {
```

```
        tmp = 4.0 * u[i + N*j]
```

```
        if (j > 0) tmp -= u[i + N*(j-1)]
```

```
        if (i > 0) tmp -= u[(i-1) + N*j]
```

```
        if (i < N-1) tmp -= u[(i+1) + N*j]
```

```
        if (j < N-1) tmp -= u[i + N*(j+1)]
```

```
        v[i + N*j] = tmp
```

```
    }  
}
```