

Tuesday, 04/11/12:

Moscow State Aviation Technology University

Dpt of Applied - division of informatics and of mathematics
(C, C++, libraries)

diff. eqn., analysis, num. methods, probability, optimization

Computer accounts are needed:

- UniAccount (\rightarrow eduroam, IT Servicecenter)
- department account
- account in Pool-Raum 2421 = computer lab

Lectures: Tu 15:15 - 16:45, We. 13:15 - 14:45

Lab: We. 15:15 - 16:45

Open lab: Th. 11:15 - 12:45 } in computerlab 2421

HPCF-2010-2 Sec. 2:

$$-\Delta u = -u_{xx} - u_{yy} = f \text{ at } (x_i, y_j)$$

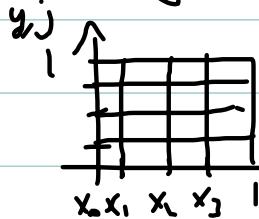
$$f(x_i, y_j) \approx \frac{-u(x_i, y_{j-1}) - u(x_{i-1}, y_j) + 4u(x_i, y_j) - u(x_{i+1}, y_j) - u(x_i, y_{j+1})}{h^2}$$

FD = finite difference method = take this approximate equation as the determining equation for the approximation $u_{ij} \approx u(x_i, y_j) \Leftrightarrow$

$$f(x_i, y_j) = \underbrace{\frac{-u_{ij-1} - u_{i-1j} + 4u_{ij} - u_{i+1j} - u_{ij+1}}{h^2}}$$

$=: f_{ij}$ = shorthand notation

Example of mesh with $N=3$:



$$x_i = i h$$

$$i = 0, 1, 2, 3, 4$$

$$y_j = j h,$$

$$j = 0, \dots, 4$$

We have Dirichlet BC (boundary conditions)

$u = 0$ on $\partial\Omega \Rightarrow$ The values of u_{ij} with $i=0$ or $N+1$ or $j=0$ or $N+1$ are known and thus will be dropped from the system of equations.

$N=3 \Rightarrow$ interior points for $i=1, 2, 3, j=1, 2, 3 \Rightarrow$ 9 unknowns u_{ij} and 9 equations.

$$\begin{array}{ccc|c|c} 4u_{11} - u_{21} & -u_{12} & & & \\ -u_{11} + 4u_{21} - u_{31} & -u_{22} & & & \\ -u_{21} + 4u_{31} & -u_{32} & & & \\ \hline -u_{11} & +4u_{12} - u_{22} & -u_{13} & & \\ -u_{21} & -u_{12} + 4u_{22} - u_{32} & -u_{23} & & \\ -u_{31} & -u_{22} + 4u_{32} & -u_{33} & & \\ \hline & -u_{12} & 4u_{13} - u_{23} & = f_{13} h^2 & \\ & -u_{22} & -u_{13} + 4u_{23} - u_{33} & = f_{23} h^2 & \\ & -u_{32} & -u_{23} + 4u_{33} & = f_{33} h^2 & \end{array}$$

The above is a system of linear equations.

We used a particular ordering of the unknowns? (Others are possible.)

We can write it as $A \vec{u} = \vec{b}$ if we introduce A and \vec{b} appropriately.

Typical choice is to multiply by $h^2 \Rightarrow$

A is just matrix of integers 0, -1, 4 then.

$$\left[\begin{array}{ccc|c} 4 & -1 & & -1 \\ -1 & 4 & -1 & -1 \\ & -1 & 4 & -1 \\ \hline -1 & & 4 & -1 \\ & -1 & -1 & 4 \\ & & -1 & -1 \\ \hline & & -1 & 4 \\ & & -1 & -1 \\ & & & -1 \end{array} \right] = \left[\begin{array}{c} u_{11} \\ u_{21} \\ u_{31} \\ u_{12} \\ u_{22} \\ u_{32} \\ u_{13} \\ u_{23} \\ u_{33} \end{array} \right] = \left[\begin{array}{c} b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_9 \end{array} \right]$$

Here, we used $b_k = h^2 f_{ij}$ with $k = i + N(j-1)$

and $\vec{u}_k = u_{ij}$

Now have $A \vec{u} = \vec{b}$ with A in tech. rep.